

# PERCEPTION REMOTE CONTROL

## Overview

For those users who want to communicate with Perception, or to control connected hardware from within their own application, HBM offers a convenient remote control package that includes two different communication interfaces: RPC and COM.

RPC is a communication technology that enables data exchange and invocation of functionality residing in a different process on the same computer, on the local area network, or across the Internet.

COM is a technology that enables software components to communicate directly with each other. COM is supported by any major programming environment like .NET, Visual Basic, LabView, Matlab, C/C++ etc.

## RPC

Remote Procedure Call (RPC) defines a powerful technology for creating distributed client/server programs. RPC can be used in all client/server applications based on Windows operating systems. It can also be used to create client and server programs for heterogeneous network environments that include operating systems like Unix, Linux and Apple.

RPC is a preferred way of communication when heavy communication traffic is involved. The provided RPC interface is designed to be used by C/C++ programmers. The supplied documentation contains a command overview, command reference and examples. RPC includes direct control of hardware settings like timebase, acquisition modes, amplifier, trigger modes, etc.

## COM

The Perception Remote Control package includes a COM wrapper with the RPC client program that makes it easy to create remote control programs. You can use the common COM interface to work with a variety of programming languages, including C#, VB (.NET), C/C++, MATLAB, Agilent-VEE and LabView.

In addition to a detailed user manual, a help file reference provides additional examples.

COM is most likely the easiest and most popular way to interface. The high-level Microsoft Component Object Model provides full functionality and does not require knowledge of RPC.

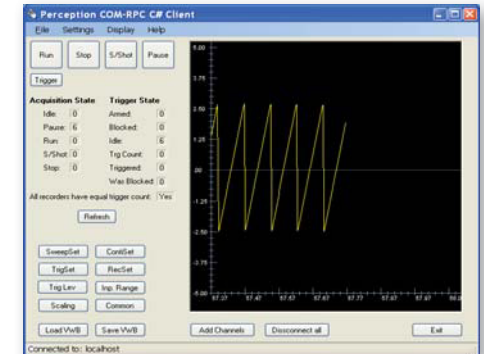
```
public bool Connect(string address, out string Result)
{
    Result = "";

    // Connect to RPC Server (Perception)
    try
    {
        m_RPC.SetServerAddress(address);
        m_RPC.ConnectToServer();

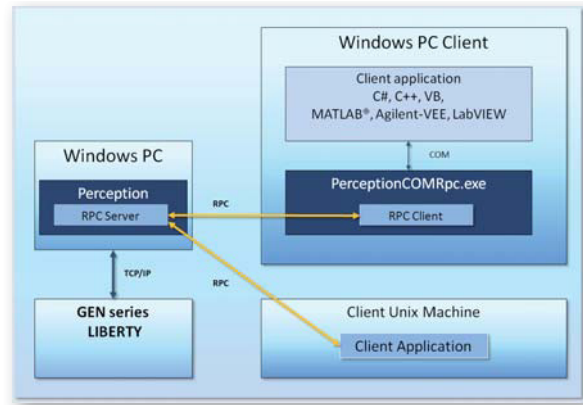
        m_bConnected = true;
        RetrieveHardwareNames();
        UpdateAcqAndTriggerState();
        timer1.Enabled = true;
        toolStripStatusLabel1.Text = "Connected to: " + address;
    }
    catch (Exception)
    {
        // RPC connection could not be setup.
        Result = "Could not connect to Perception RPC Server";
        m_bConnected = false;
        toolStripStatusLabel1.Text = "Not connected";
        return false;
    }
    return true;
}

private void MainForm_FormClosed(object sender, FormClosedEventArgs e)
{
    if (m_RPC == null) return;
    if (!m_bConnected) return;
    m_RPC.DisconnectFromServer();
    toolStripStatusLabel1.Text = "Not connected";
}

private void btnRun_Click(object sender, EventArgs e)
{
    if (!PerceptionReady()) return;
    m_RPC.Start();
    UpdateAcqAndTriggerState();
}
}
```



You can utilize RPC to control GEN DAQ hardware from a client application. A COM wrapper helps you to use this functionality within any well-known development environment, without requiring detailed knowledge of RPC.



Examples of source code are included to give programmers a head start.



### Command summary

#### File operations

- **GetFilenames** retrieve filenames from a specified directory
- **LoadVwb** load a specified workbench
- **SaveVwb** save workbench with a specific name
- **LoadSetting** load hardware settings from a selected file
- **SaveSettings** save hardware settings with a specific name

#### Acquisition control

- **Start** start an acquisition
- **Stop** stop the active acquisition
- **OneShot** start a single-shot sweep
- **Pause** pauses the active acquisition
- **Trigger** generate a (software) trigger

#### Status

- **GetAcquisitionState** retrieve the current acquisition state of all recorders
- **GetTriggerState** retrieve the current trigger state of all recorders

Live data is supplied as a reduced data stream of min/max pairs as used by *Perception* for display purposes.

#### Data retrieval (live data)

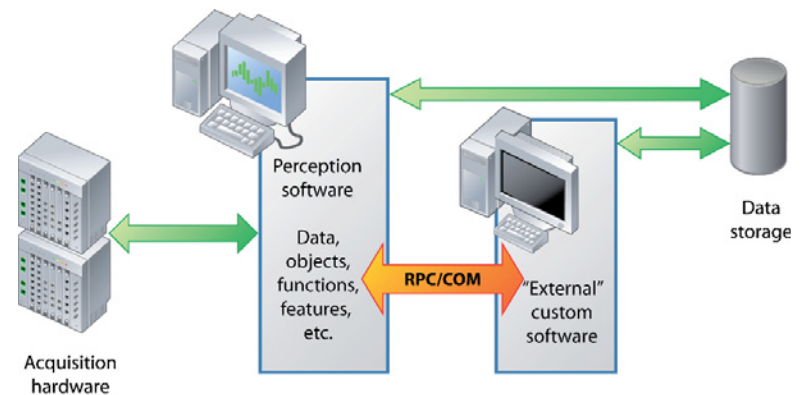
- **GetAvailableWaveforms** get a list
- **SubscribeLiveWaveform** connect
- **UnsubscribeLiveWaveform** disconnect
- **IsSubscribed** verify waveform connection
- **GetData** fetch data
- **GetMultiData** get multiple data

#### Settings (RPC only)

- [set][get]ChannelEnable
- [set][get]TriggerSettings
- [set][get]TimebaseSettings
- [set][get]StorageSetting
- [set][get]SweepSetting
- [set][get]ContinuousSettings
- [set][get]SCCouplingSettings
- [set][get]SCUserScalingSettings
- [set][get]SCInputRangesSettings
- [set][get]SCFilterSettings
- [set][get]SCExcitationSettings
- [set][get]SCBridgeSetupSettings
- [set][get]SCBridgeCalibrationSettings
- [set][get]SCBridgeBalancingSettings
- [get]CalibrationInfo
- [set][get]TriggerLevelSettings
- [set][get]TriggerRepeatTimerSettings
- [set][get]TriggerPulseDetectorSettings
- [set][get]AlarmLevelsSettings
- [get]InfoSettings

- **StartAutoBalance**
- [set][get]ShuntResistorActive
- [set][get]PowerControlSettings
- **ChannelsScType**
- [set][get]CalibrationSettings
- [set][get]RecSweepSettings
- [set][get]RecCommonSettings
- [set][get]RecTimebaseSettings
- [set][get]RecTriggerBusSettings
- [get]RecInfoSettings
- [set][get]RecStorageSettings
- [set][get]RecDefaultSettings

- [set][get]CommonSettings
- [set][get]NetworkSettings
- [set][get]MasterTimebaseSettings
- [set][get]TriggerIOSettings
- [set][get]DiskSettings
- [get]MainframeInfoSettings
- **Configuration**
- **MainframeSetDefaultSettings**
- **IsCommunicationActive**
- **GetCommunicationAddress**
- **StorageActive**
- **GetDiskMemoryUsage**



The *Perception* remote control interfaces enable communication with external, custom software, to access data, settings and information.

Head Office  
HBM  
Im Tiefen See 45  
64293 Darmstadt, Germany

Tel: +49 6151 8030  
Email: info@hbm.com

France  
HBM France SAS  
46 rue du Champoreux, BP76  
91542 Menecy Cedex

Tel: +33 (0)1 69 90 63 70  
Email: info@fr.hbm.com

UK  
HBM United Kingdom  
1 Churchill Court, 58 Station Road  
North Harrow, Middlesex, HA2 7SA

Tel: +44 (0) 208 515 6100  
Email: info@uk.hbm.com

USA  
HBM, Inc.  
19 Bartlett Street  
Marlborough, MA 01752, USA

Tel: +1 (800) 578 4260  
Email: info@usa.hbm.com

PR China  
HBM Sales Office  
Room 2912, Jing Guang Centre  
Beijing, China 100020

Tel: +86 10 6597 4006  
Email: hbmchina@hbm.com.cn

