

Measuring Power Losses in Electric Motors and Inverters



Learn more at

<https://www.hbm.com/eDrive>

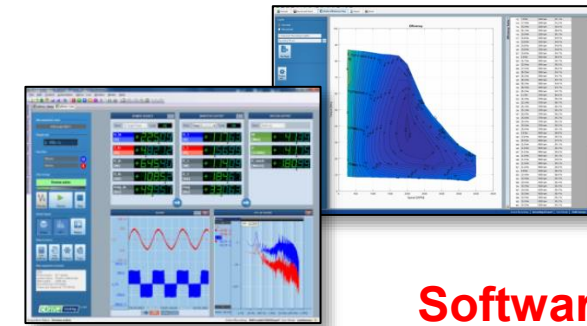


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Agenda

1. Introduction
2. Inverter losses
3. Motor Losses
4. Measurement Uncertainty

Acquisition



Software



Sensors

Losses

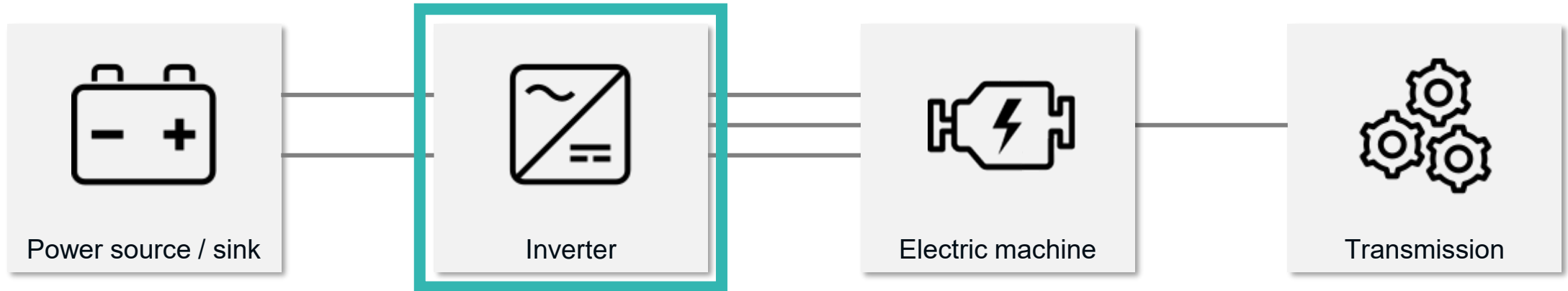
- ▲ Each component has losses in energy between states ⚡
- ▲ Losses create heat 🔥
- ▲ Losses decrease range 📉
- ▲ Losses result in increased weight/volume 📦
- ▲ Characterize losses so we can:
 - Understand them
 - Mitigate them
 - Manage them

Heat


Vehicle Range


Weight & Volume


Inverter Losses



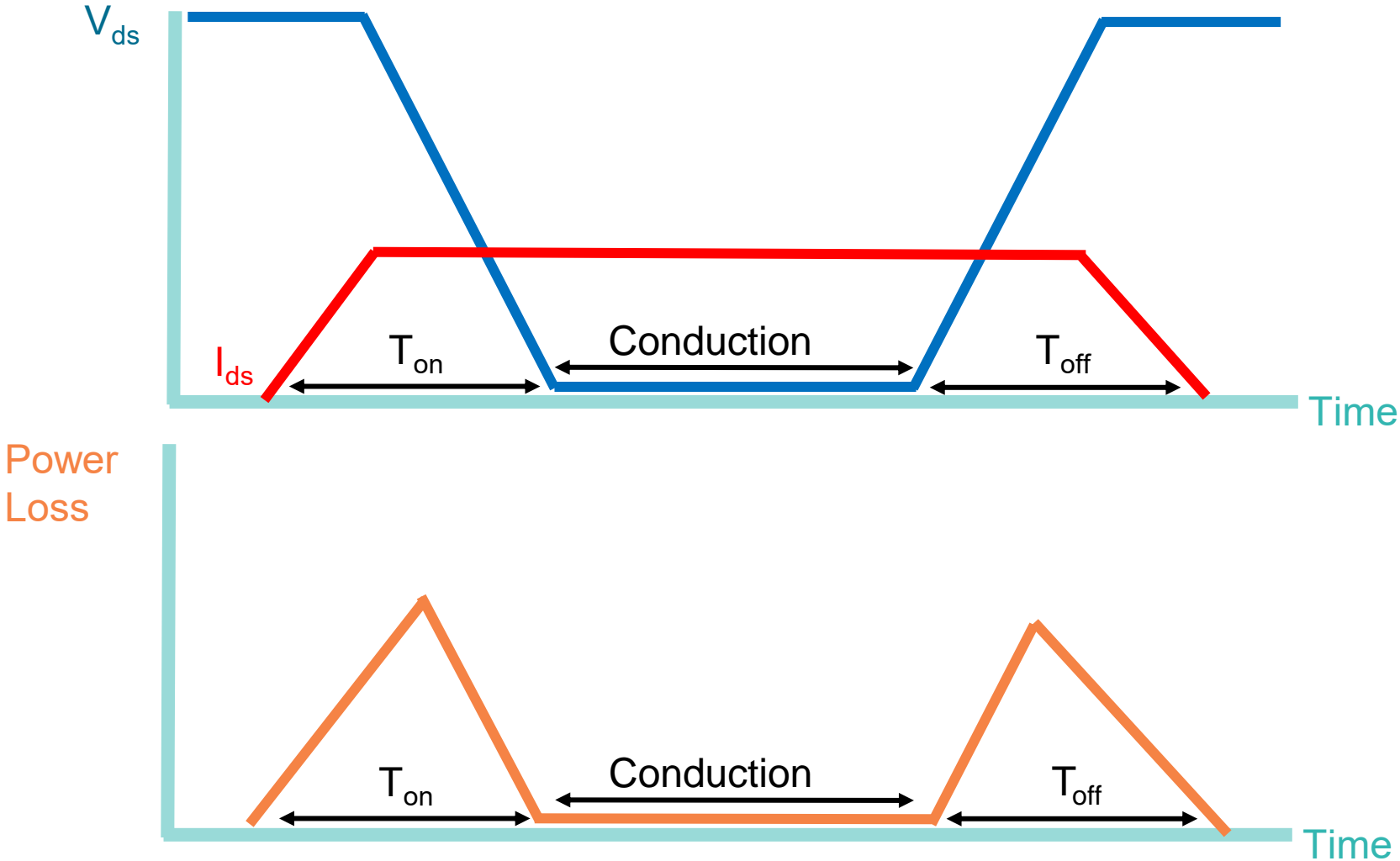
P_{DC} $P_{AC} = P_{DC} - P_{conduction} - P_{switching} - P_{stray}$ P_{AC}

- ▲ Conduction Losses 
 - Resistance of the switch
 - Resistance of the connections

- ▲ Switching Losses 
 - Turn on losses
 - Turn off

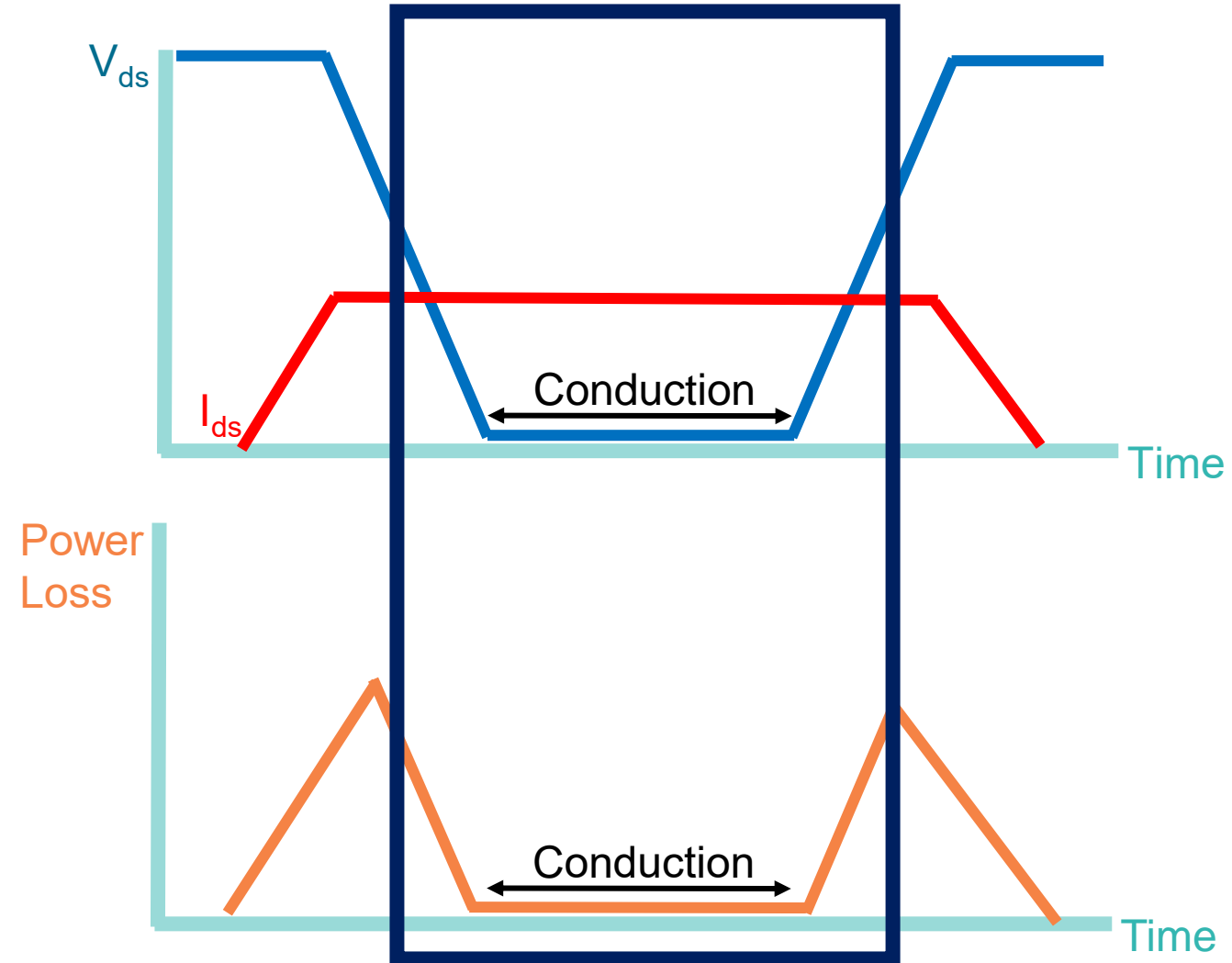
- ▲ Stray Losses 
 - off state
 - support circuits

Inverter Switch operation



Conduction Losses

- ▲ Switch has an “on resistance” 💡
- ▲ Power loss = $I_{ds}^2 R_{switchOn} = I_{ds} * V_{ds}$
- ▲ Number of switches 📊
- ▲ Resistance is a function of temperature 🌡️
- ▲ Other resistances in the circuit will cause losses ☑️
- ▲ Key to Measurement
 - Time aligned electric & mechanical
 - Calculations
 - Accuracy



Switching losses

▲ $P = f \cdot (E_{on} + E_{off}) = I_{ds} \cdot V_{ds}$

- Frequency = f
- Energy loss on/off 🔥

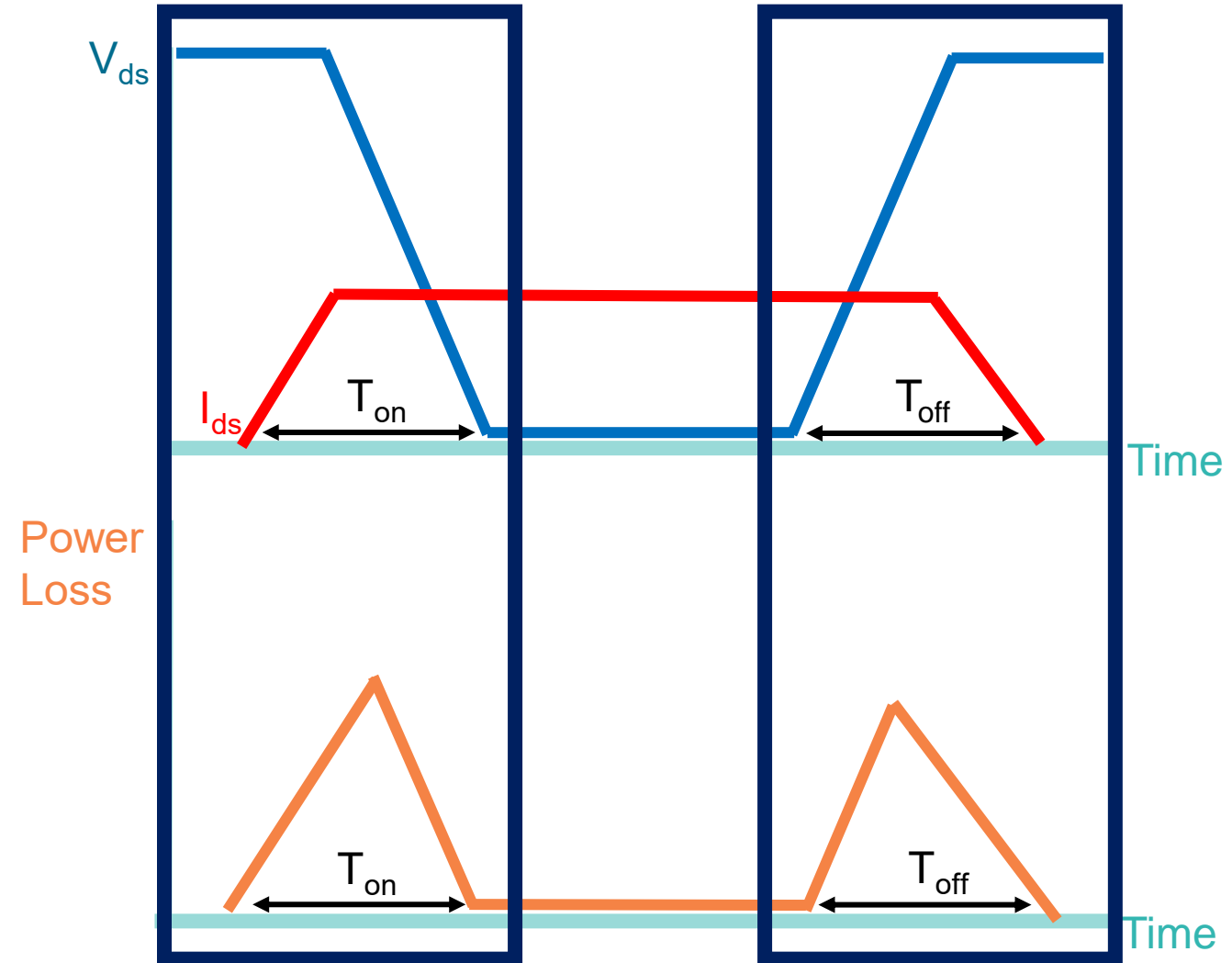
▲ Losses increase with frequency ☑

▲ Losses increase with turn on/off time 🕒

- T_{rise}
- T_{fall}

▲ Key to Measurement

- High speed
- Differential
- Recorded data

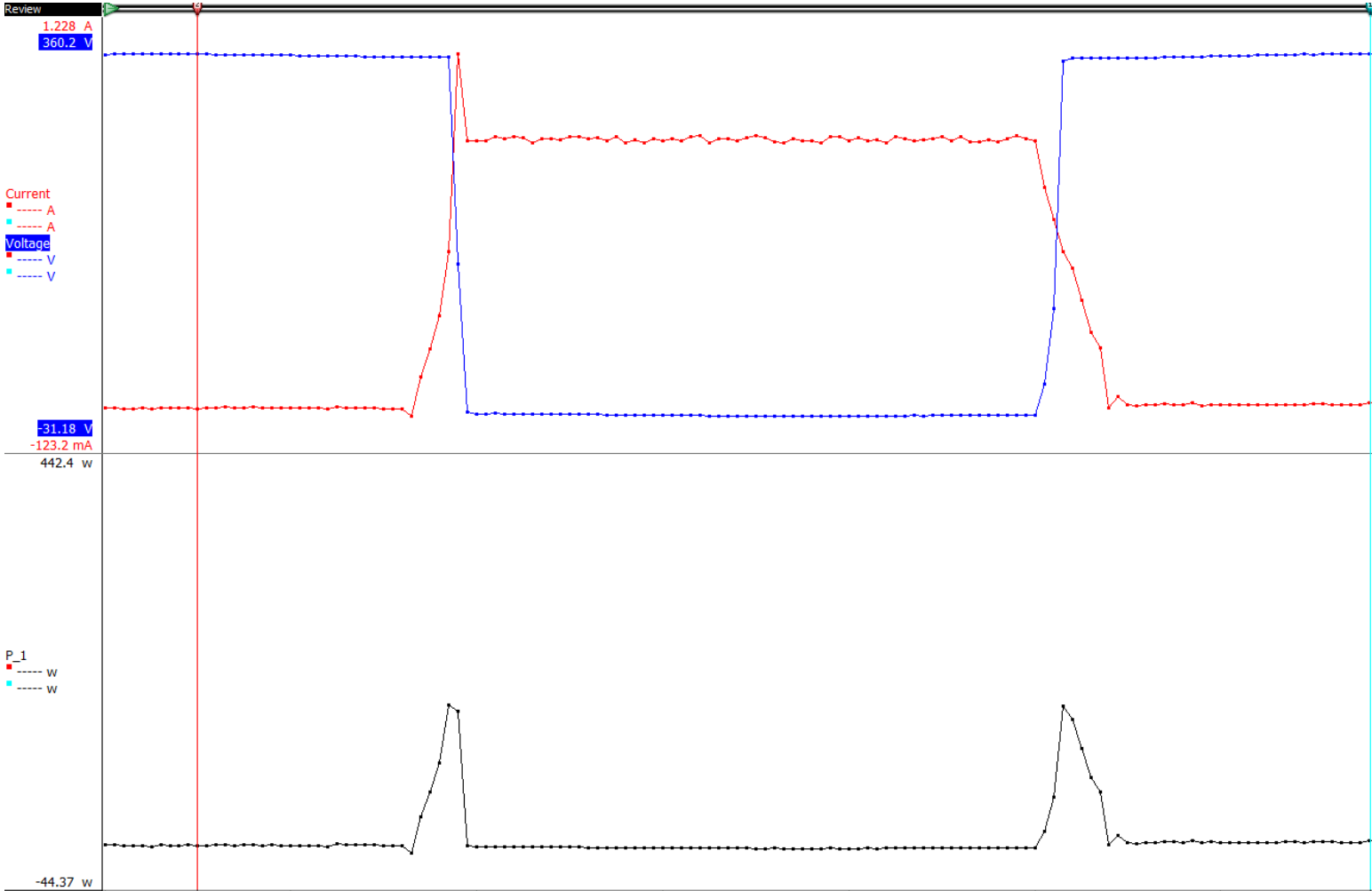


Inverter Loss Measurement

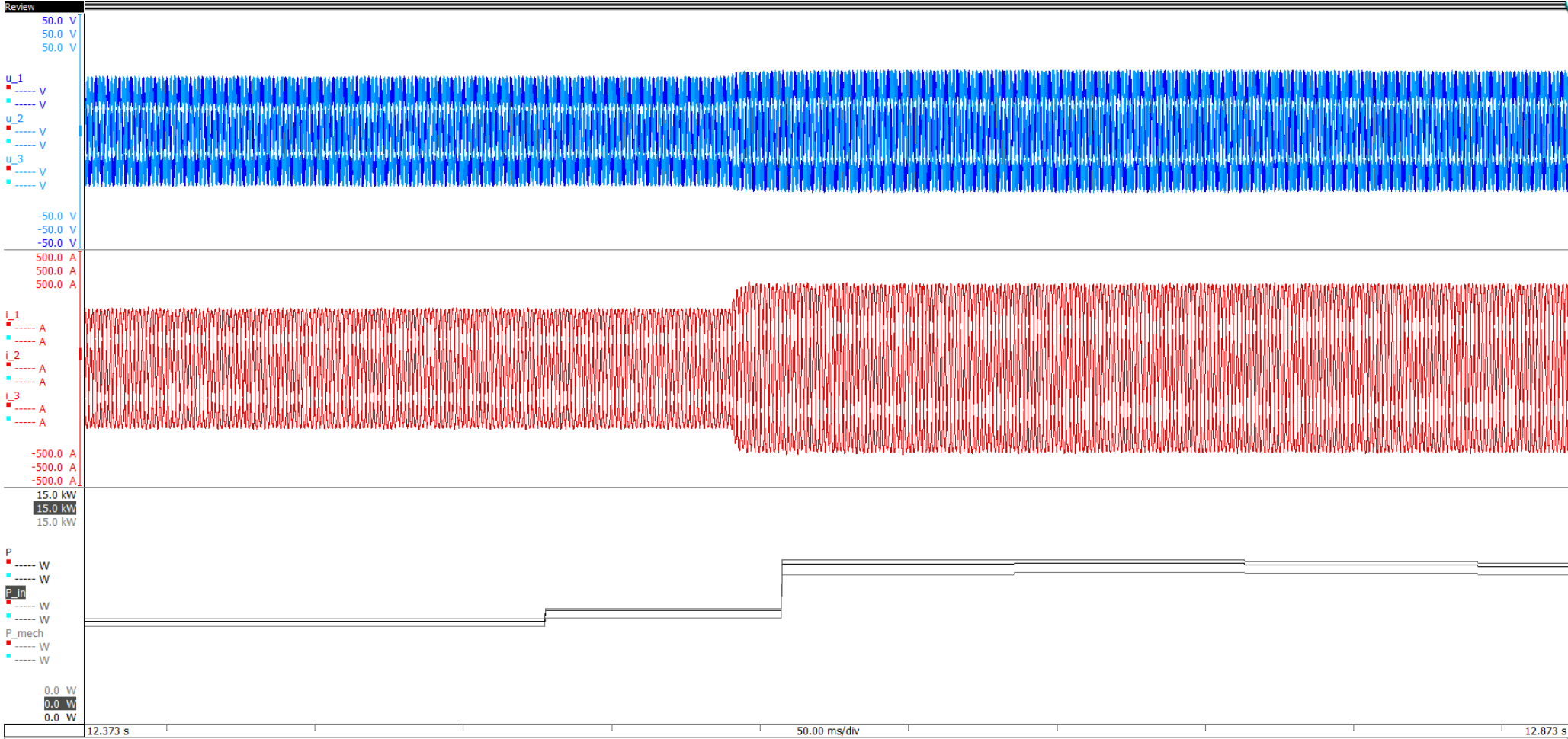
- ▲ Accurately measure DC in & AC out ⚖️
- ▲ Estimate On resistance with TC and equation 📊
 - Calculate losses
 - Time aligned temperatures
- ▲ Measure P_{on} & P_{off} with differential measurement across switch
 - Scope card @ 250MS/s



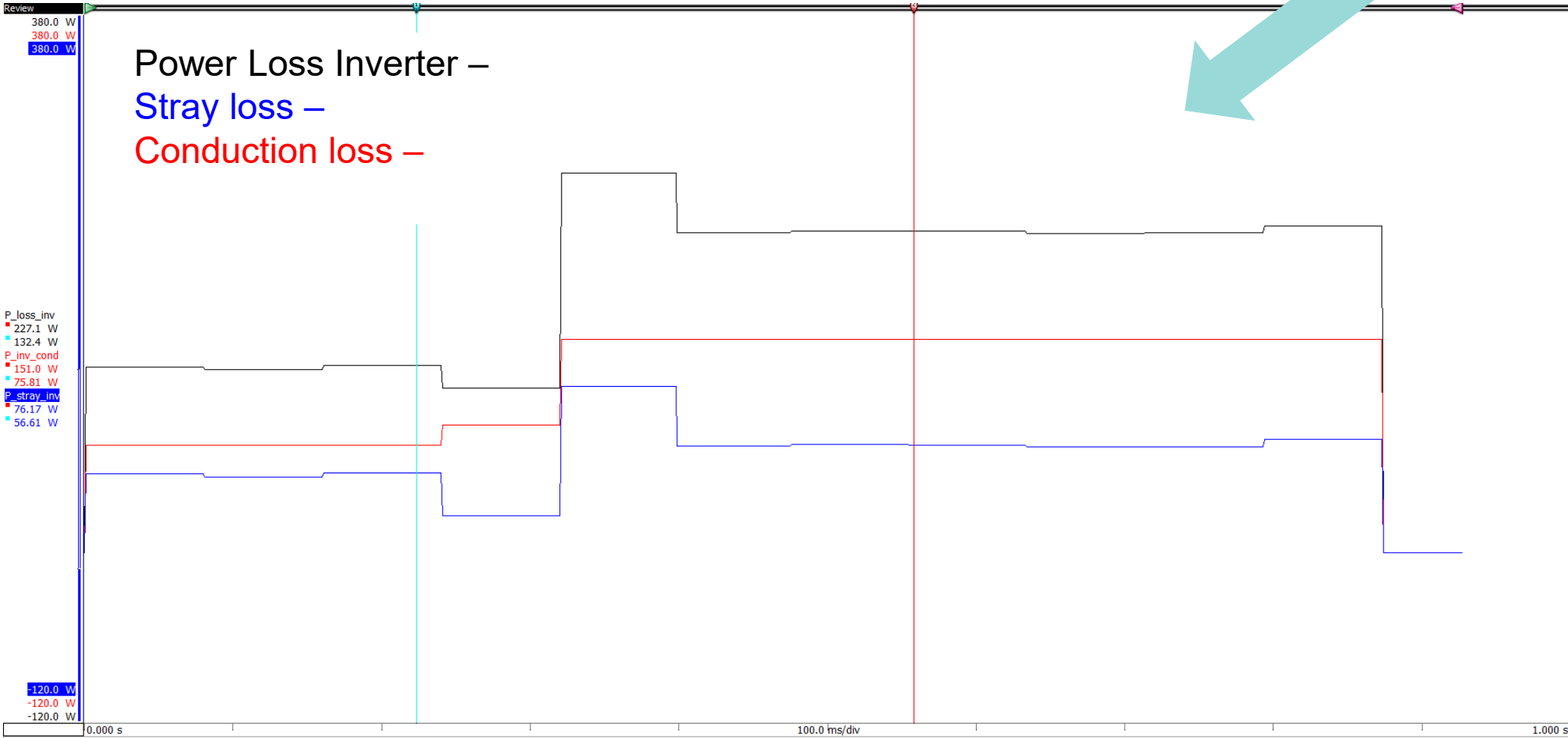
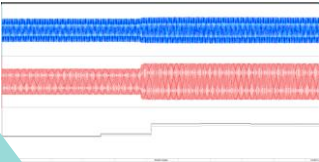
Inverter Switch On and Off Example



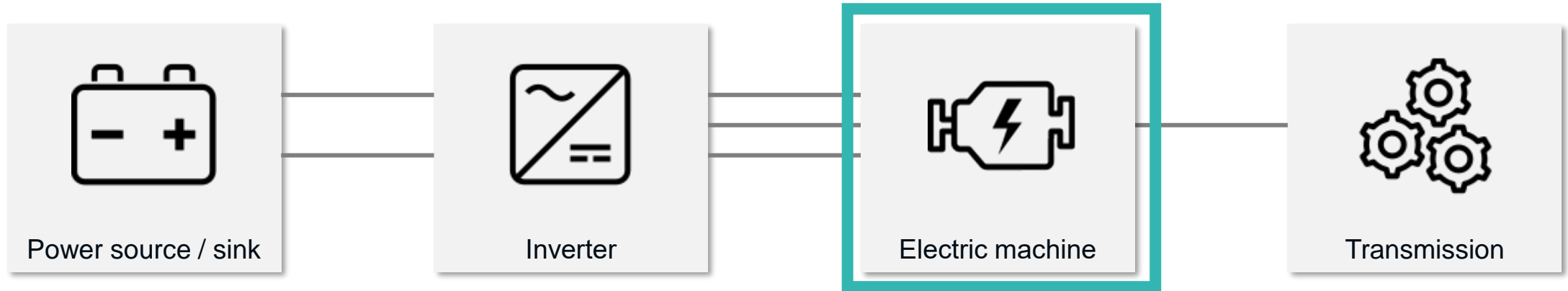
Real Example – Load Step




Inverter Losses





Motor Losses



P_{AC} $P_{mech} = P_{AC} - P_{copper} - P_{iron} - P_{mechloss}$ P_{mech}

- ▲ Copper Losses 
 - Resistive
 - Skin effect

- ▲ Iron Losses 
 - Eddy currents
 - Hysteresis

- ▲ Mechanical Losses 
 - Friction
 - Windage

Copper Losses - Resistive

- Losses due to resistance of the motor windings 🔥

- $P_{\text{copper}} = I_{\text{ph}}^2 * R_{\text{windings}}$

- Temperature dependent 🌡️

- $R_{\text{winding}} = R_0 * (1 + \alpha * (T - T_0))$

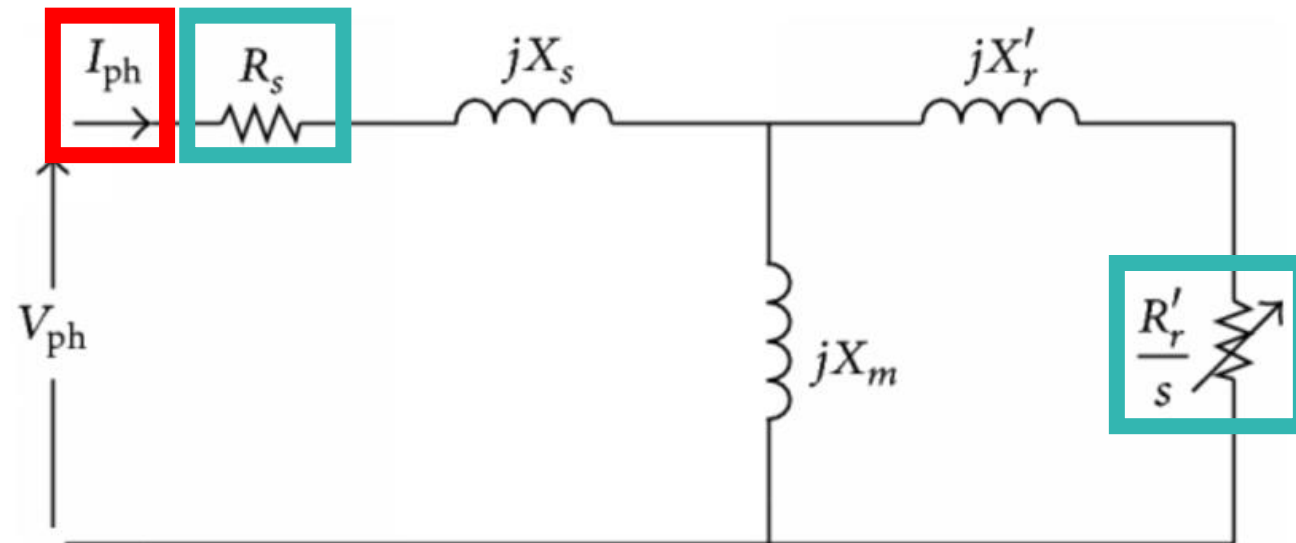
- Temp ↗️ → Ω ↗️

- Can be reduced by cooling 🧊

- Measured with phase current and temperatures 📏

- Key to Measurement






- Time aligned electric & mechanical
- Custom sensors and calculations
- Accuracy






Motor Circuit equation highlighting the resistive element

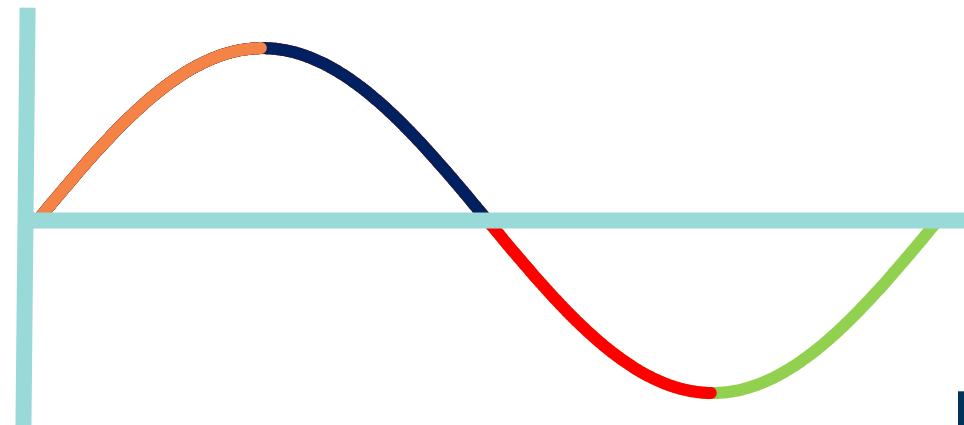
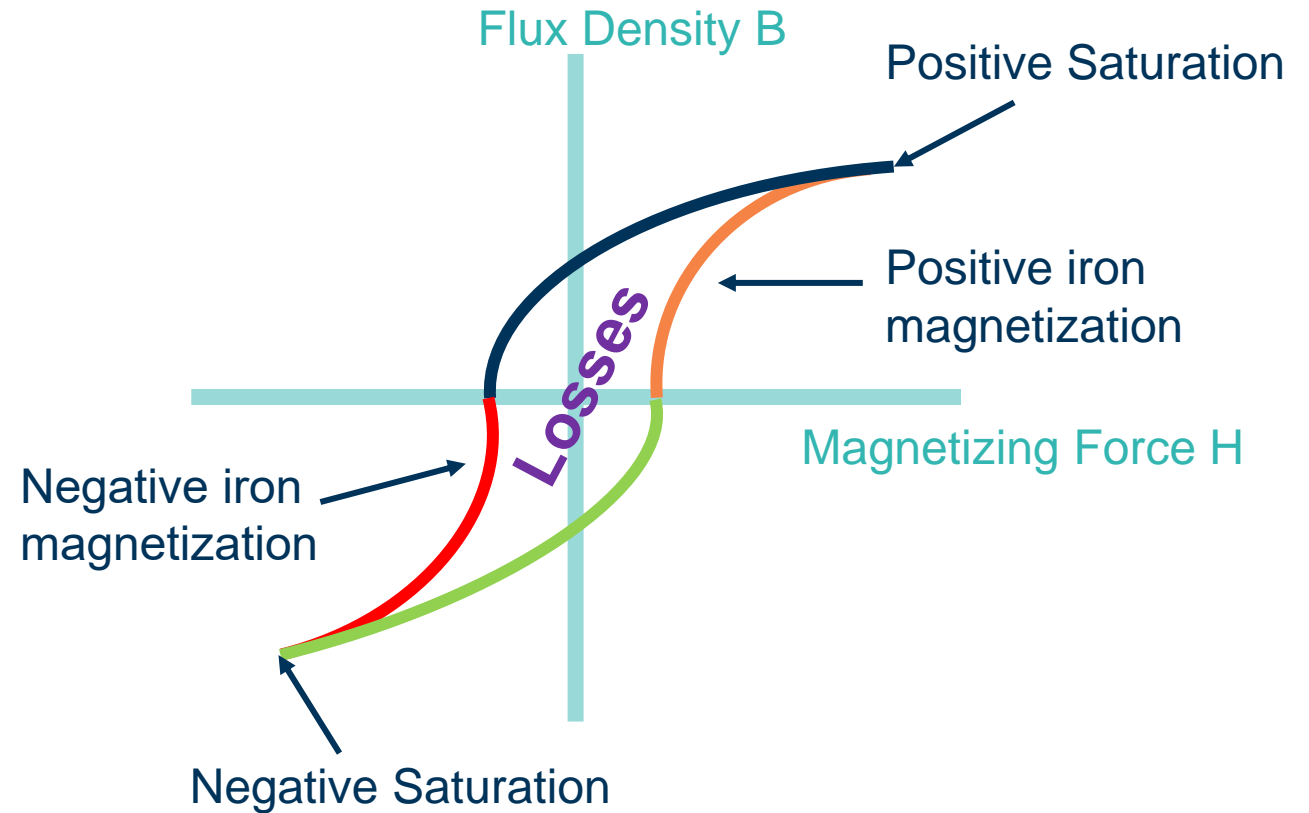
Copper Losses - Skin Effect

- ▲ AC frequency makes the conductor look smaller 🗣️
- ▲ $R_{ac} = R_{dc} * k * \sqrt{f}$
 - K = gauge factor
 - F = frequency in MHz
- ▲ Effects high fundamentals and switching frequencies 🌊
- ▲ Taken into effect with resistance used in the copper loss equation 🔥
- ▲ Key to Measurement
 - Custom equations
 - Custom sensors
 - accuracy

Frequency	Skin Depth	Graphic
5 Hz	29.7 mm	
50 Hz	9.38 mm	
500 Hz	2.97 mm	
5 kHz	.938 mm	
50 kHz	.297 mm	




Iron Losses - Hysteresis

- ▲ Magnetizing iron requires energy 
- ▲ Losses happen every sine wave 
 - Property of the iron & permeability 
- ▲ $P_b = \eta * f * V * B_{max}^n$
 - η – Steinmetz hysteresis coefficient (material property)
 - n - Steinmetz exponent (material property)
 - V – Volume
 - f – Frequency
 - B – Max flux density
- ▲ Key to Measurement
 - Data to understand variables → Sensitivity
 - Accuracy
 - Custom Calculations
 - Time aligned electric & mechanical



Iron Losses - Eddy Currents

▲ Faraday's law states "any change in the environment of a coil of wire will cause a voltage to be induced in the coil, regardless of how the magnetic change is produced"

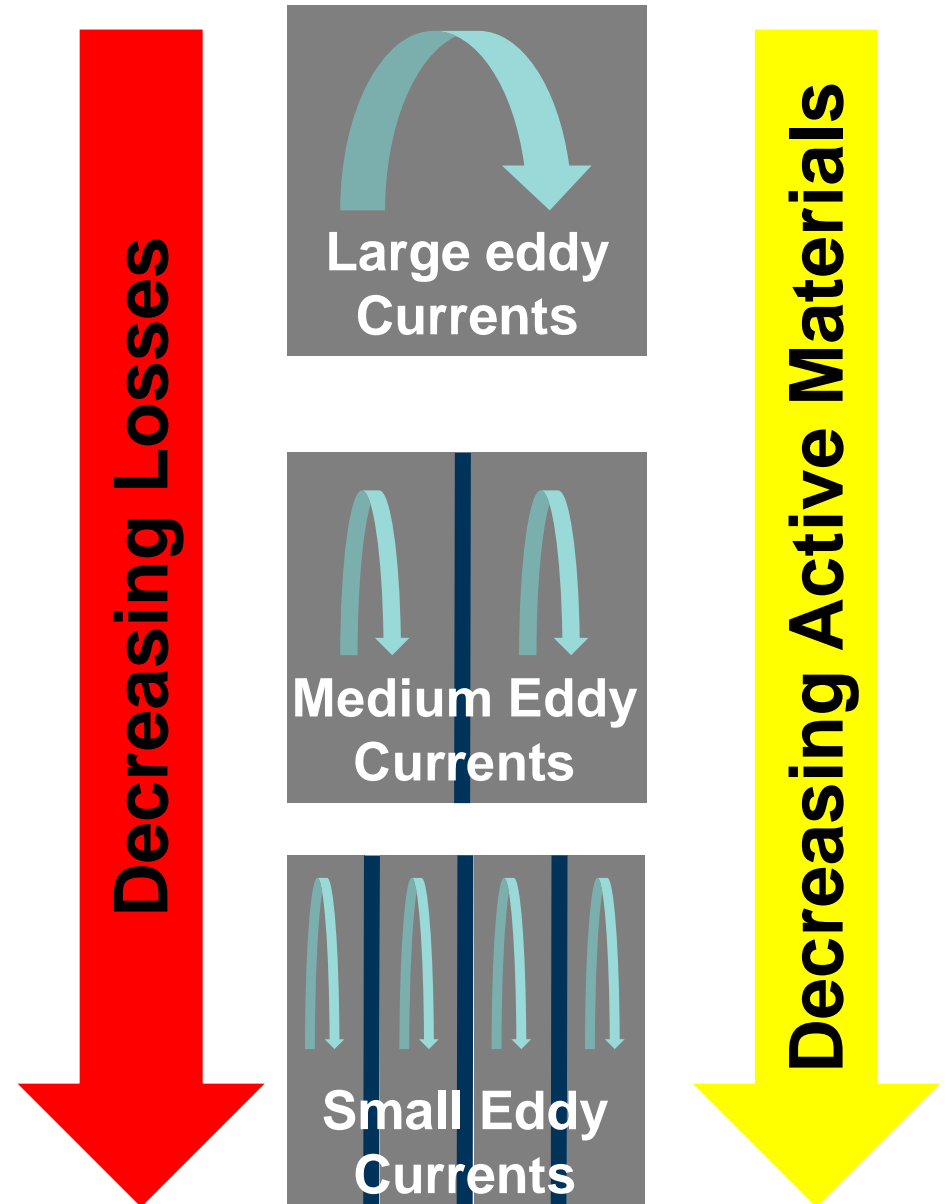
- The magnetism of the flux will self induce EMF 
- Current will flow in the core → losses 
- Thinner laminations have a higher resistance 

▲ $P_e = K_e * B_{max}^2 * f^2 * t^2 * V$

- K_e – eddy current constant
- B - Max flux density
- f – frequency
- t – Thickness
- V – Volume

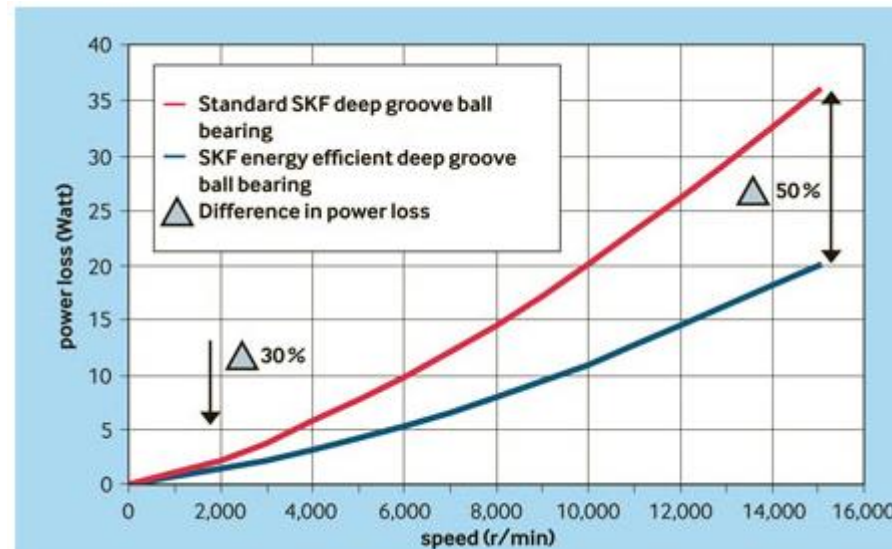
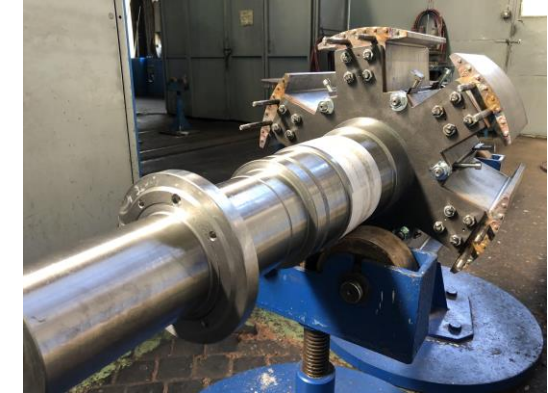
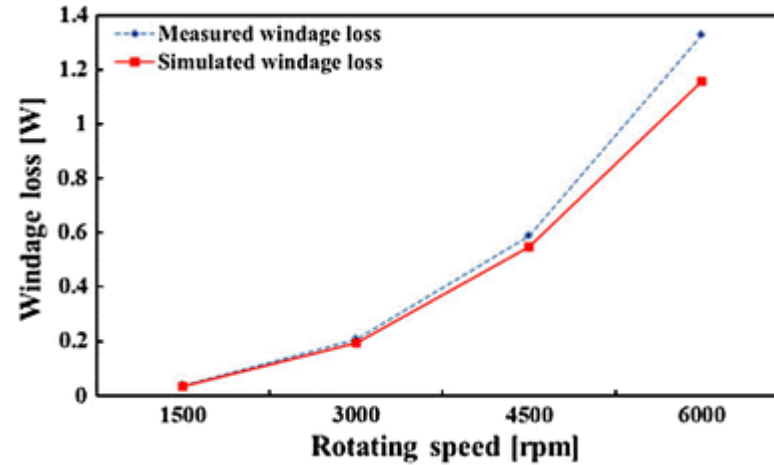
▲ Key to Measurement

- Data to understand variables → Sensitivity
- Accuracy
- Custom Calculations





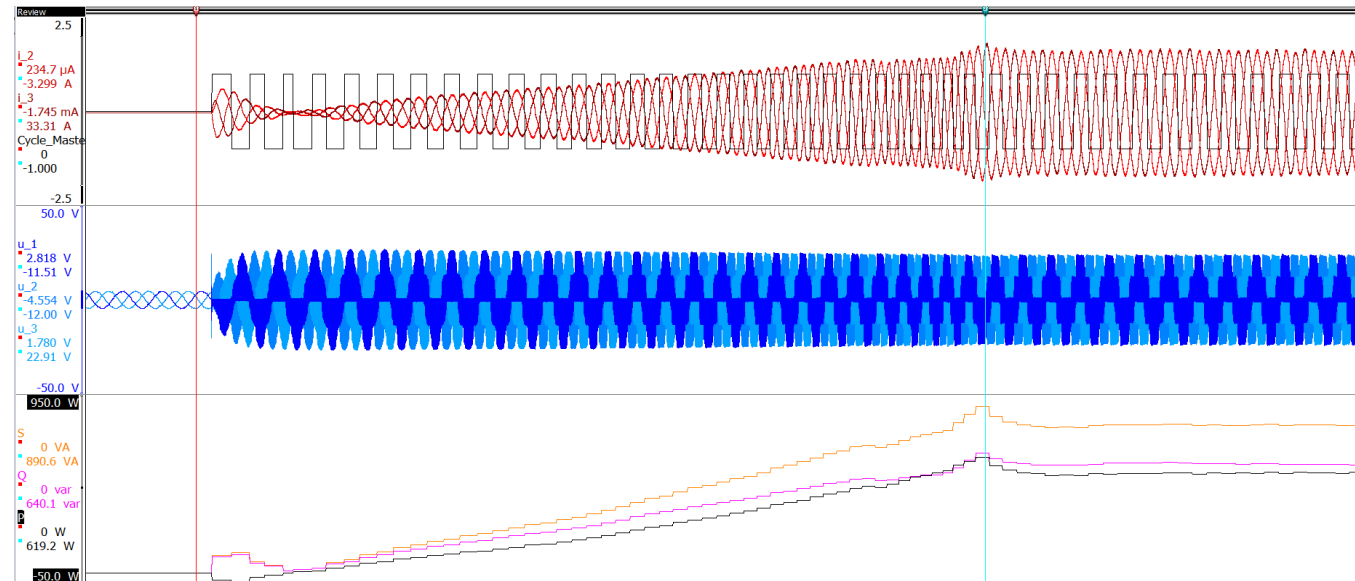
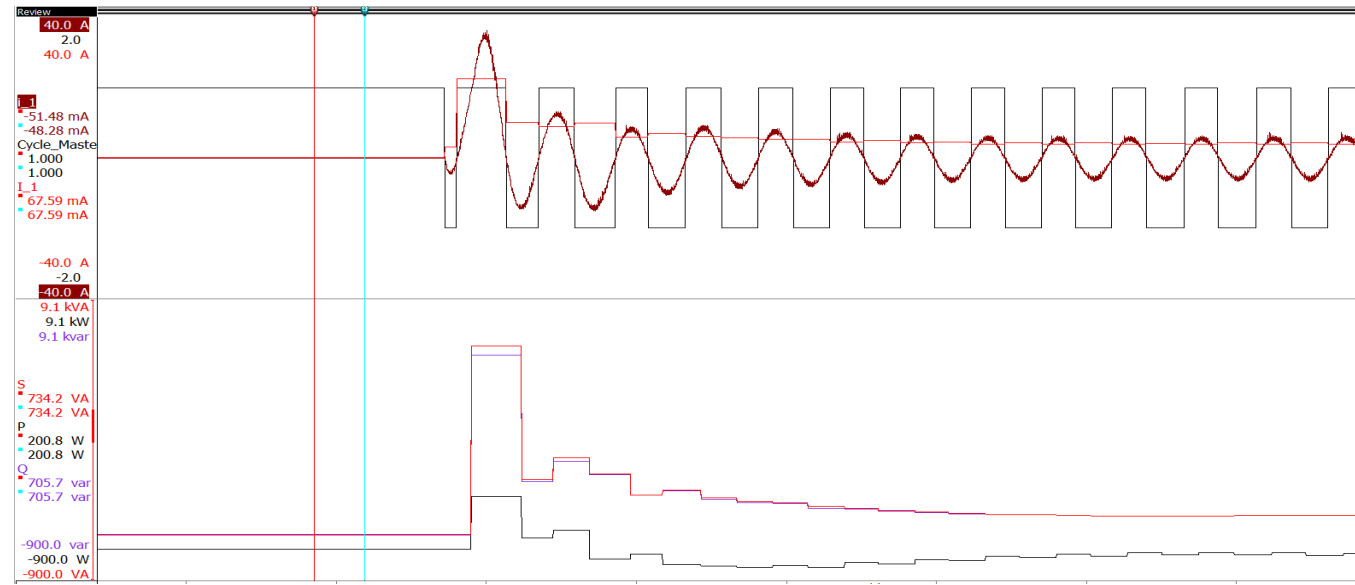
Mechanical losses

- Internal windage 🖱️
- Bearing Friction 🌀
- Misalignment
- Keys to measurement
 - Accuracy
 - Custom sensors





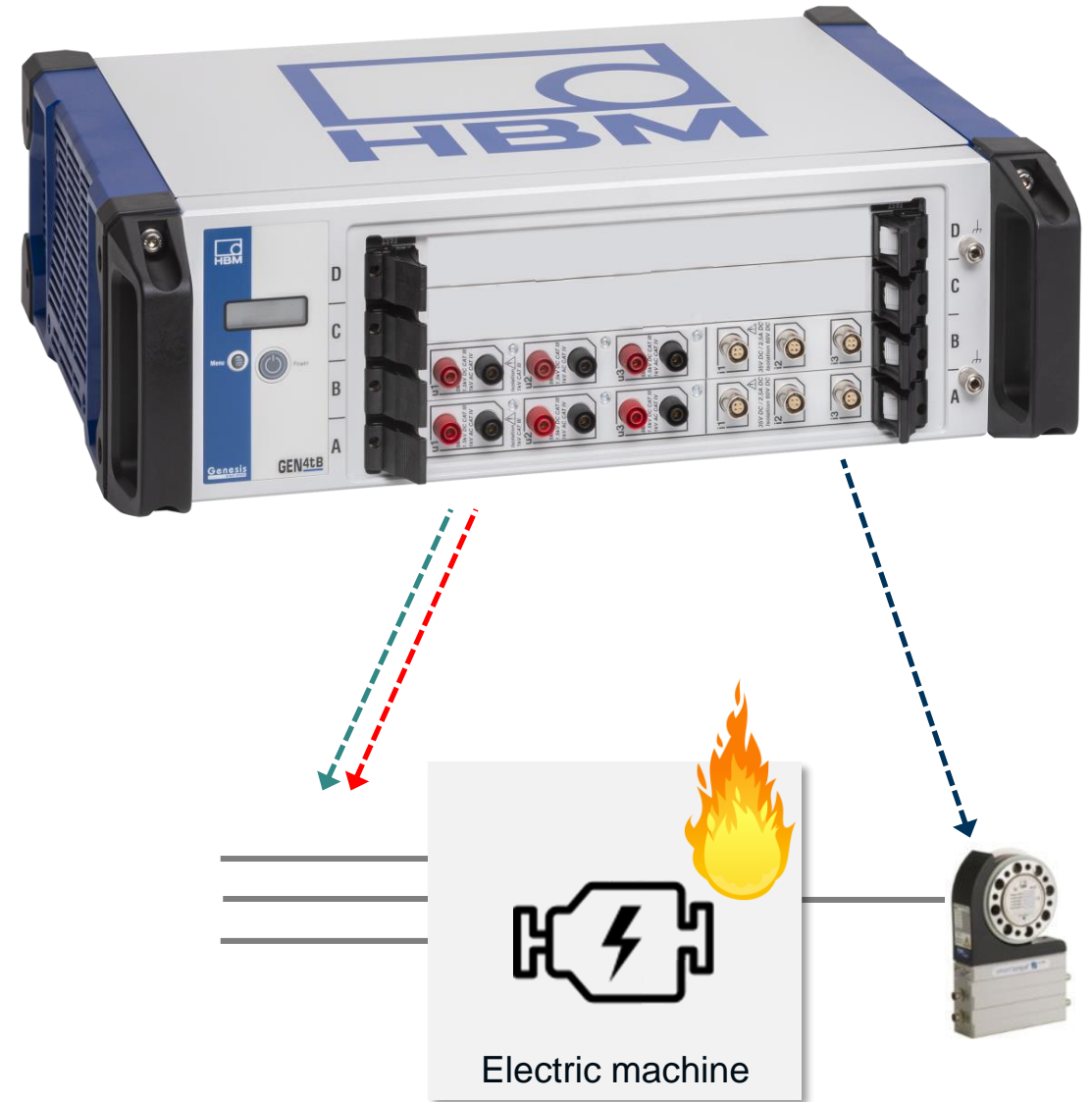
Dynamic Losses

- ▶ Load changes will result in magnetizing currents that are greater than normal operation 
- ▶ Inrush currents happen even with variable frequency excitation 
- ▶ Key to Measurement
 - Real time cycle detection
 - Time alignment – Electric and Mech



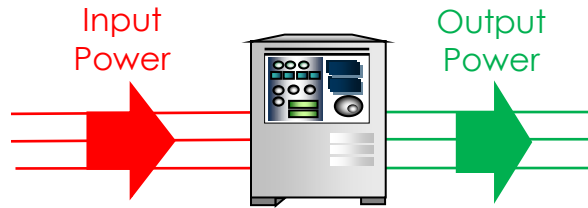
Motor Loss Measurement

- ▲ Accurately measure AC in & Mechanical out 
- ▲ Measure copper/iron losses thermocouples and equations 
- ▲ Measure mechanical losses with equation or a curve based on measurement



Measurement Uncertainty

Measuring Power Losses → A Differential Problem



- 500 kW inverter
- 95% efficiency

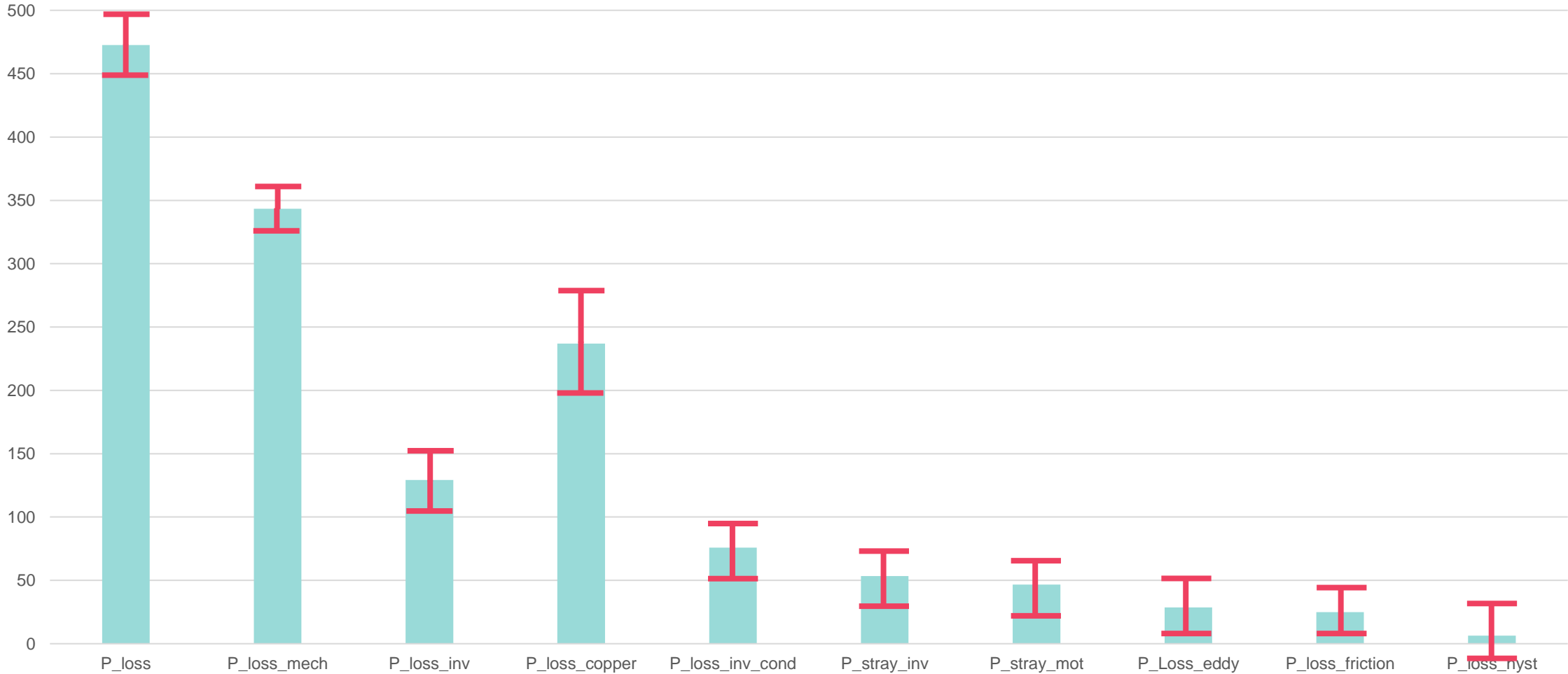
Measurement chain error @ 1%

Measurement chain error @ 0,1%

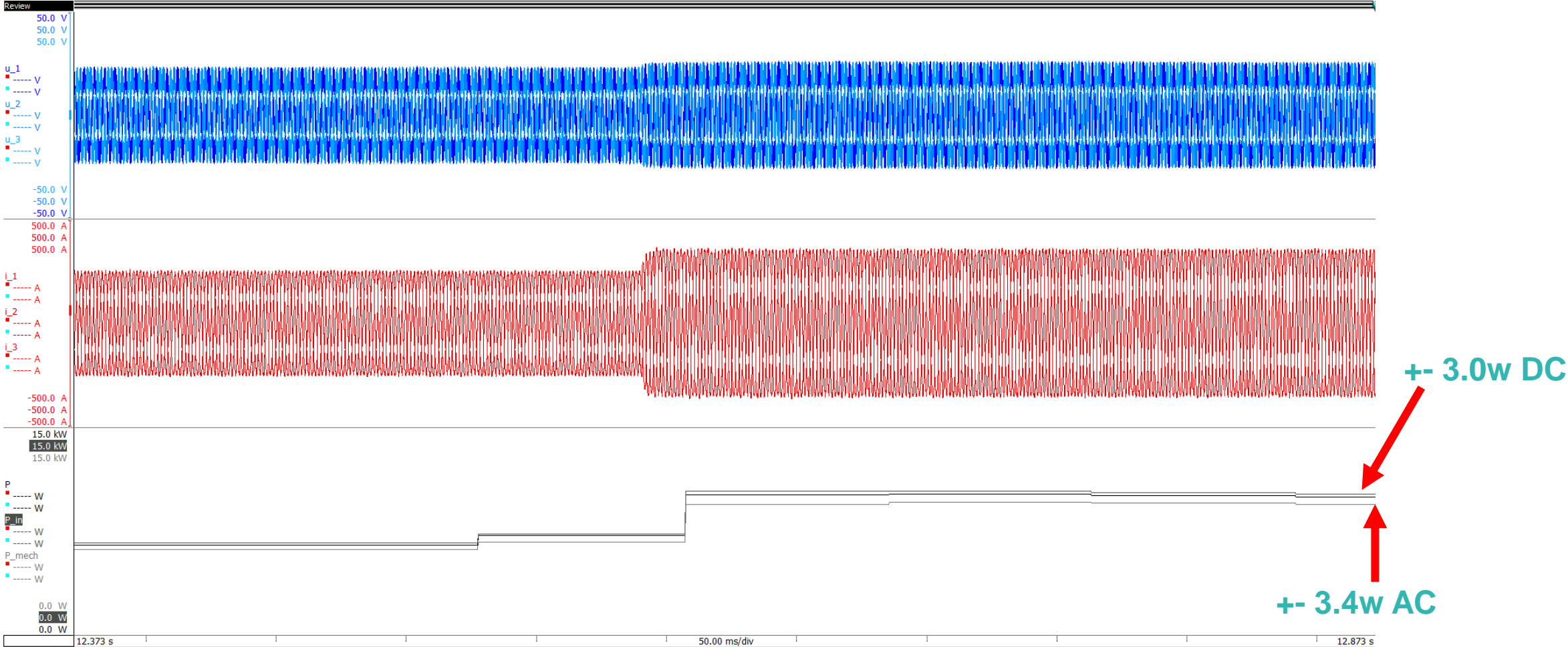
	“Truth”	Measured	Error	Measured	Error
Input	500 kW	500 kW +/- 5 kW	1%	500 kW +/- 0.5 kW	0,1%
Output	475 kW	475 kW +/- 4.75 kW	1%	475 kW +/- 0.475 kW	0,1%
Losses	25 kW	25 kW +/- 9.75 kW	39,0%	25 kW +/- 0.975 kW	3,9%
Conduction	5 kW	5kW +/- 9.75 kW	🤖	5 kW +/- .975 kW	19.5%

If you want to achieve reasonable measurements for derived values like **Power Loss** you need the most accurate measurement you can get

Measurement Uncertainty and Losses

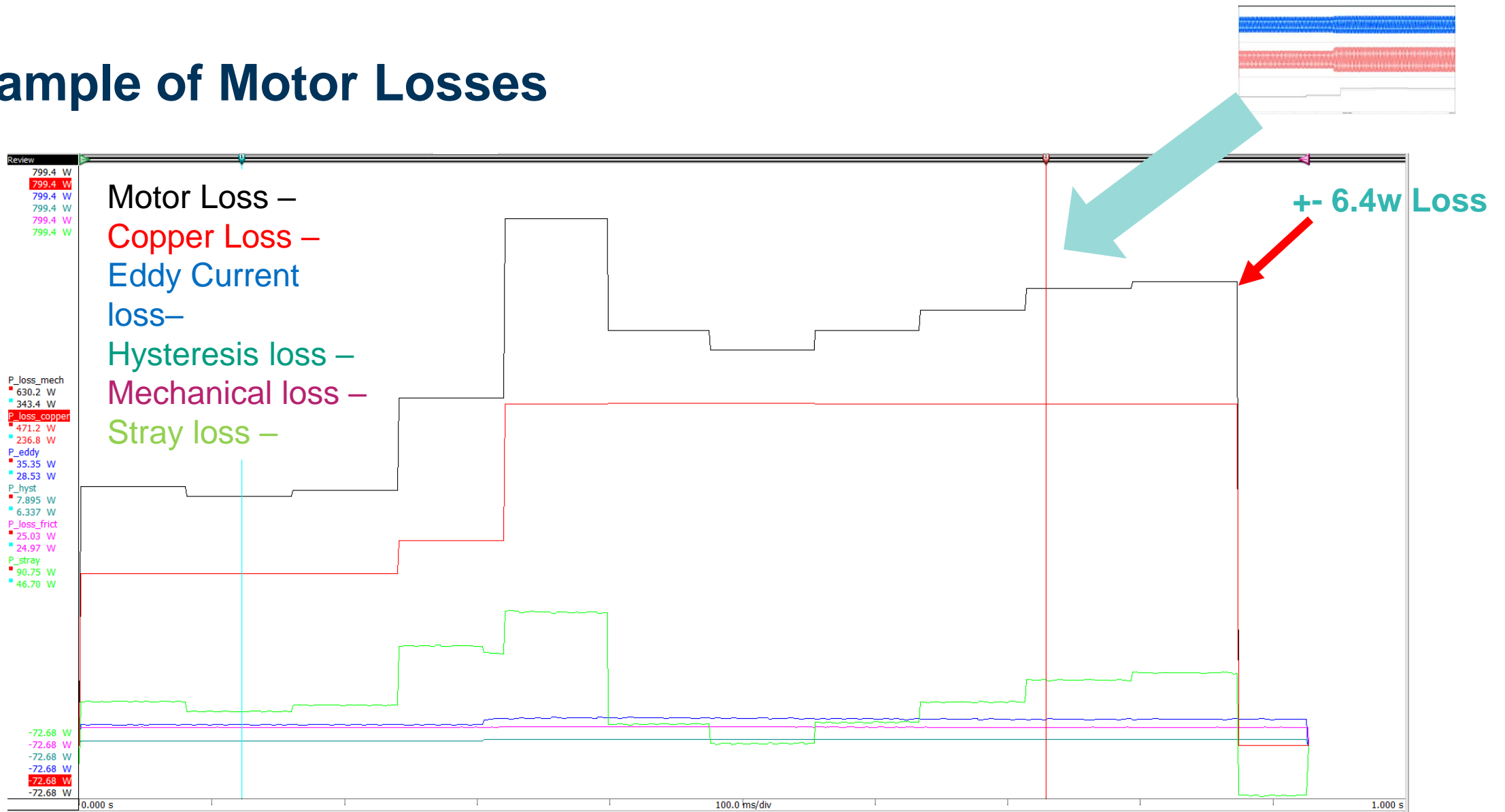


Real Example – Load Step



Measurements of raw signals

Example of Motor Losses

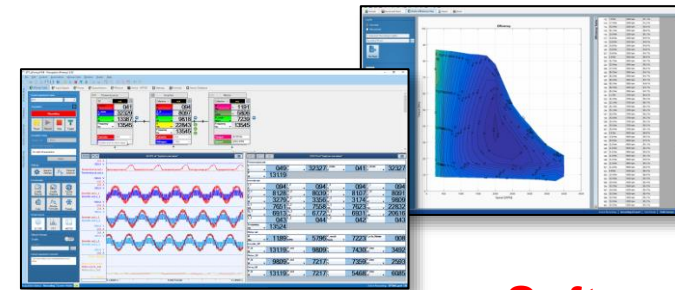


High accuracy measurement gives you ability to trust values

eDrive Value

- Simple data collection of electro-mechanical signals
- Fast and accurate Power Measurements
 - Lowest Measurement Uncertainty (MU)**
 - Lowest MU across the frequency range**
 - Lowest Torque MU**
- Custom Equations
- Recorded Data
 - Recorded data will allow you to refine models in post process with 1 test

Acquisition



Software



Sensors

Thank You - Questions? 



Mitch Marks

Business Development at HBK -
Hottinger, Brüel & Kjær

