

Force shunt measurement using CFW piezoelectric force washers

Force washers must always be pre-stressed during mounting. This also applies for CFW piezoelectric force washers. After mounting, the force washers work in the force shunt, i.e. a part of the force no longer passes through the sensor but instead through the pre-stressing device, for example the pre-stressing elements CPS.

The measuring chain's sensitivity varies depending on the pre-stressing device's design. For example, when HBM's CPS set of pre-stressing elements is used, the CFW piezoelectric force washers' sensitivity is reduced by 7-12 %. After mounting, the force washers should be calibrated to allow reliable sensitivity determination.

Calibration using calibrated force transducers

One method of calibrating sensors is to use calibrated force transducers. This requires a force transducer and, in addition, an amplifier. Strain gauge-based reference force transducers (C18, Z30A series) are particularly well suited to this approach.

Force transducers for industrial applications, like for example S9M from HBM, can also be used. If no appropriate amplifier for strain gauge-based sensors is available, series CFT sensors can also be used. The CFT series comprises pre-stressed, piezoelectric transducers that have been calibrated before delivery, i.e. their sensitivity is known.

When choosing the reference transducer please consider that the accuracy you will be able to attain later cannot be better than the precision of your calibration which in turn is determined by the reference measuring chain's accuracy.

Three steps for calibrating the measuring chain

As already mentioned above, a measuring chain comprising piezoelectric force washers (CFW) as sensors always needs to be calibrated when the sensor has been mounted. This means that the mechanical mounting conditions should not be changed after the calibration procedure. This applies to pre-stress in particular.

Three steps need to be taken to calibrate a measuring chain:

• Determining the sensor's sensitivity after mounting: The force in N, a mass in kg or similar is measured simultaneously with the charge generated by the piezoelectric



force washers at this force. The sensitivity can now be easily calculated by dividing the charge by the force (sensitivity = charge/force).

- Setting up the charge amplifier: The measuring range and gain of the CMD600 digital charge amplifier are freely adjustable. The sensitivity calculated as described above needs to be input in the Assistant software. A reasonable measuring range should be set to guarantee optimal resolution.
- Verifying the adjusted parameters: Finally, we recommend that you once again compare the measuring chain to the reference measuring chain.

In the following sections of this article we assume that your sensor has been mounted and adequately pre-stressed. The pre-stress can be directly measured using the force washer. A manufacturing certificate has been included for this purpose. Adjust the sensitivity on the CMD600 as required and increase pre-stress to the desired value. Minimum: 10% of the force washers nominal (rated) force.

When using the CMD600 charge amplifier, connect it to a PC and use CMD Assistant for configuration. Please observe the CMD600 operating manual. Set the sensor's sensitivity to 1, the unit to pC. Using this configuration, the amplifier measures the charge in pC.



Device		
IP Address [169.254.10.0 [New amplifier Nb 0000]		•
Reading and status		
Signal		
Current value	2.	48 N 🚽
Limit switch 1 🕘 2 💮 Digital Input / Output I1	O 1 ○ 02 ● Parameter set PS1 ● PS2 ●	
- Device		
Identification		
Communication		
Scaling		
Manual scaling		
Sensitivity	1	pC/N
Gain	2500,056	рС
Physical gain	2500,056	N
System gain	0,00399991	V/N
SensorTeach		
Display		
Display unit	pC	
Signal processing		
 Signal output 		
Peak values storage		
Limit switches		
Digital inputs / outputs		



Configure the CMD as described above: The sensitivity is 1 and you measure the sensor signal in pC. This is how to start the calibration procedure.

Device		
IP Address 169.254.10.0 [New amplifier N	0000]	
Reading and status		
Signal		E E00 40 N
Current value 🔻		5.598, 19 N
Limit switch 1 😝 2 💮 Digital Input / Outj	ut 11 💿 01 💿 02 💿 Parameter set PS1 😝 PS2 💿	
Device		
Identification		
Communication		
Scaling		
Manual scaling		
Sensitivity	4,3	pC/N
Gain	42982,47	pC
Physical gain	9995,923	N
System gain	0,00100041	V/N
SensorTeach		
Display		
Signal processing		
Signal output		
Peak values storage		
Limit switches		
Digital inputs / outputs		

The CMD's sensitivity has been set in compliance with the manufacturing certificate (4.3 pC/N). A CFW/50 kN is being used. A slightly higher pre-stress has been used.

Step 1: Determining the sensor's sensitivity after mounting

Connect the sensor to the charge amplifier. Make sure that the entire measuring chain has the same temperature as its environment. It is essential to make the calibration only after the charge amplifier has operated for two hours to prevent running-in processes.

Position the reference force transducer such that the entire force flows through it (preventing force shunts).



An example of force washer calibration. The strain gauge-based force transducer is in line with the pre-stressed CFW. An MGCplus amplifies the signal provided by the S9M that is used as force sensor. When extremely high demands on precision are made, we recommend using reference transducers. The CFW force washer has been pre-stressed and the load is applied to it at the same time as to the S9M force transducer. However, this is only an example. In practice, there are many calibration methods, for example, using weights or generating the force with the machine that is to be monitored with the CFW (presses, welding machines, etc.).

It is also important to choose the correct measuring range. For this purpose, multiply the force you want to use for calibrating the measuring chain by 4 pC/N. This is a customary sensitivity value for piezoelectric sensors installed in the force shunt. Add about 20 % to the result and enter this charge value in CMD Assistant as the physical measuring range. In our example above, calibration is made at approximately 500 N; with 4 pC/N sensitivity we



expect a signal of approximately 2000 pC (4pC/N * 500 N = 2000 pC). We set the measuring range to 2500 pC.

The force used for calibration should not be less than 30 % of the maximum force that is to be measured with the CFW to ensure adequate accuracy. It is essential to prevent overloading of the sensors. Reset the piezoelectric measuring chain and tare the reference measuring chain immediately before starting the reference measurement.

Apply a load to the measuring device and measure the force using the reference measuring chain. The charge will be simultaneously displayed on the PC screen running CMD Assistant.

Device		
IP Address [169.254.10.0 [New amplifier Nb 0000]		•
Reading and status		
Signal		4 000 44 0
Current value		1.933,41 pC 🚽
Limit switch 1 😝 2 🕘 Digital Input / Output I	1 💿 01 💿 02 💿 Parameter wet P51 😝 P52 💮	
Device		
 Identification 		
 Communication 		
 Scaling 		
Manual scaling		
Sensitivity	1	pC/pC
Gain	2500,056	pC
Physical gain	2500,056	pC
System gain	0,00399991	V/pC
SensorTeach		
🗉 Display		
Display unit	pC	
Signal processing		
Signal output		
 Peak values storage 		
 Limit switches 		

The sensor's sensitivity is now calculated as follows:

Sensor sensitivity
$$[pC | N] = \frac{Charge[pC]}{Force[N]}$$

You can of course also make similar calibrations for measured quantities other than force (mass, torque, etc.)

In our example, we get the following result:

Sensor sensitivity
$$[pC/N] = \frac{1934[pC]}{508.8[N]} = 3.801pC/N$$

Using a series CMA amplifier we recommend calibrating the entire measuring chain. For this purpose, directly measure the charge amplifier's output voltage. The resulting measuring chain sensitivity is:

$$Measuring \ chain \ sensitivity[V \ / \ N] = \frac{Output \ voltage[V]}{Force[N]}$$



Step 2: Setting up the amplifier

The sensitivity can now be entered in CMD Assistant. To do so, use the "Sensor sensitivity" field.

Then you can define the "physical input range". This is the measuring range. Enter here the maximum force you want to measure. Should a higher force value be present later, the CMD can no longer output it to the voltage output.

When using a series CMA analog charge amplifier, scaling needs to be performed on the subsequent electronics.



Setting up the CMA. As calculated above, sensor sensitivity was defined as 3.801 pC/N and the measuring range in line with the application as 500 N. The CMD is auto-scaled accordingly. With 500 N, there is a voltage of 10 V at the output.

Step 3: Verification

After having made all settings, we recommend that you once again make a **comparison to the reference measuring chain**. Load the measuring device once again and compare the two measuring chains.

G		
e BM		CMD
Serát		
P Advesse [359,254,10.0]View amplifier 16:0000]		
Messwert und Status		
Sprei		077 54 1
aktualar Messant -		277,51 N
Senswete 1 😝 2 🕙 Digtate En / Ausgänge El	C A1 C A2 C Parameterate PS1 C PS2 C	
(Standard)		
Gerät		
 Identification 		
E Kommunikation		
Skalierung		
Manuelle Skalierung		
Sensorempfindlichkeit	3,61	pC/N
Elektrischer Eingangsbereich	1804,826	pC
Physikalischer Eingangsbere	e499,9518	N
System-Verstärkung	0,0200019	V/N
SensorTeach		
G Anzeige		
Einheit	N	
Signalaufbereitung		
E Signal-Ausgang		
 Signal-Ausgang Spitzenwertspeicher 		
Signal-Ausgang Spitzenwortspeicher Grenzwertüberwachung		

Reference measurement. There is little difference between the two measuring chains in the partial load range as well. The result: Excellent linearity of both the piezoelectric and the strain gauge-based measuring chain.





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