

TECH NOTE :: ClipX Mechanical work

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Brief description

This is a guide to measuring mechanical work with the ClipX. This requires two ClipX modules; one to measure the force, the other to measure the distance. The calculation determines the (mechanical) work over a certain period of time from the two variables force and displacement (or torque/angle of rotation). The force must act along the path.

$$W = \int \vec{F} d\vec{s}$$

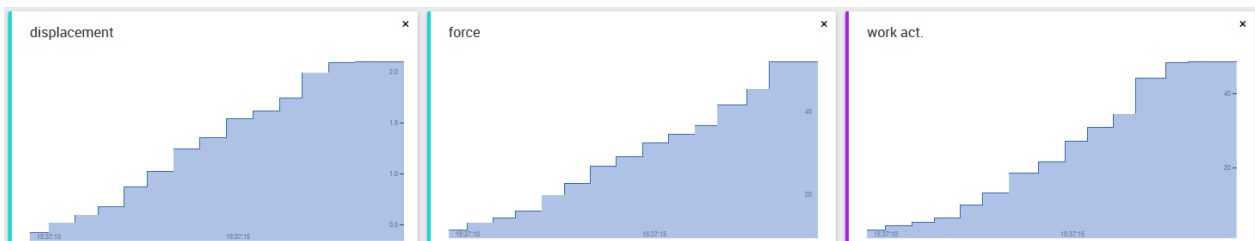


figure 1: measurement force, displacement; Calculation work

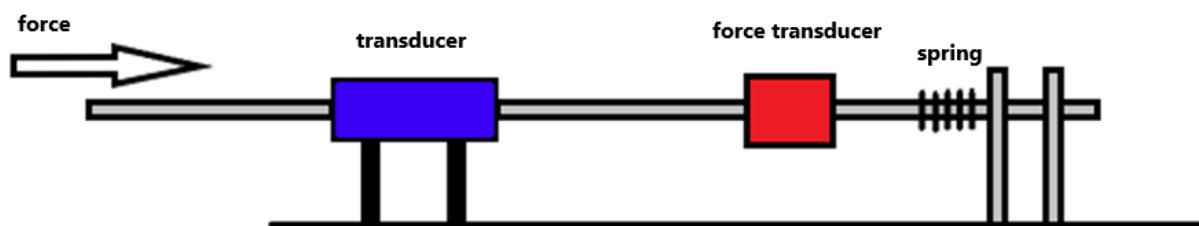
Preparations

The following materials are required to perform the measurement:

- 2 ClipX-systems
- Force transducer (here: HBM U9B)
- transducer (here: Novotechnik T25)
- 3 ethernet cables (two to connect the ClipX with the switch; one to connect your pc)
- Switch
- 2 connection cable: sensor \leftrightarrow ClipX

Each ClipX has to be connected to one sensor and both of them must be connected to the switch.

Building sketch

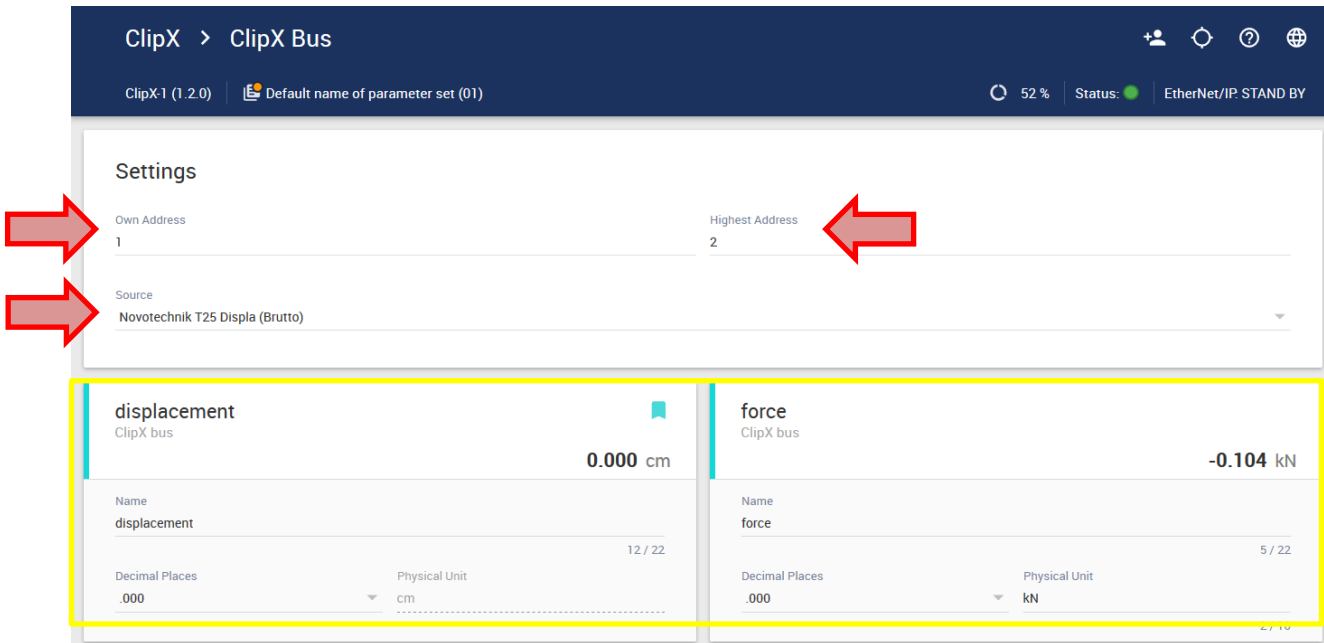


Note: The measured force must have the same direction as the displacement.

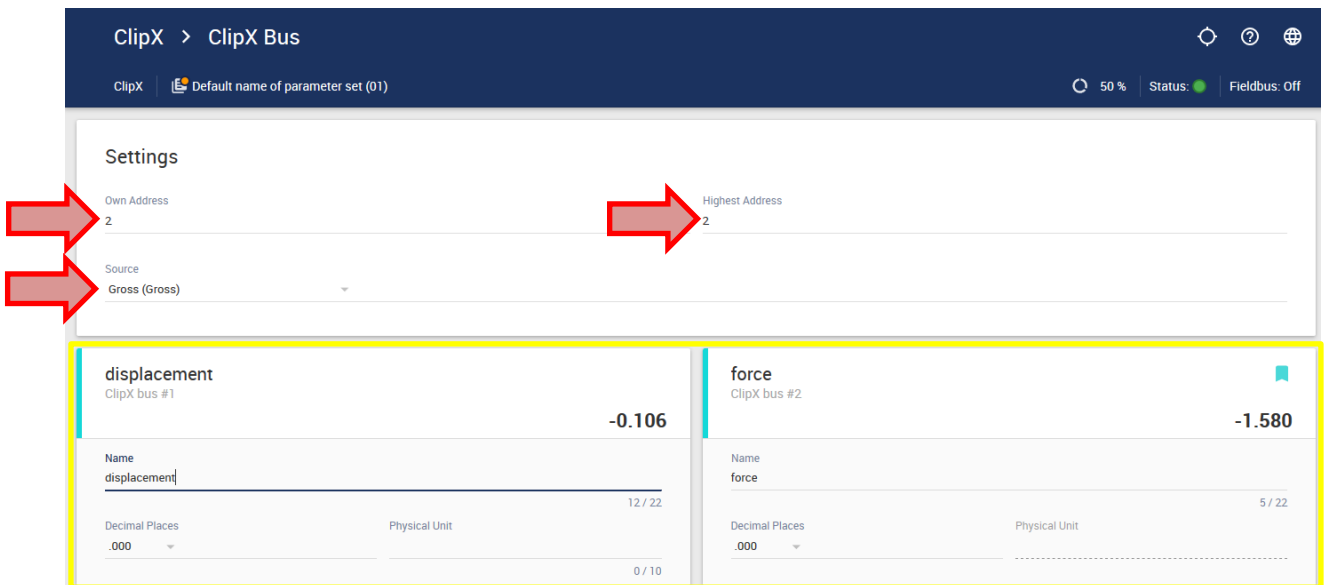
Presettings in the ClipX

To be able to work with both signals on one ClipX, a few settings have to be made.

In menu item “ClipX-Bus” of one of the two devices, the own address must be set to “1” and the highest address to “2”. As source, we select our required signal (here: transducer signal).



In the second ClipX the own address must be set to “2” and the highest address to “2”. As source, we select our required signal (here: force transducer signal).



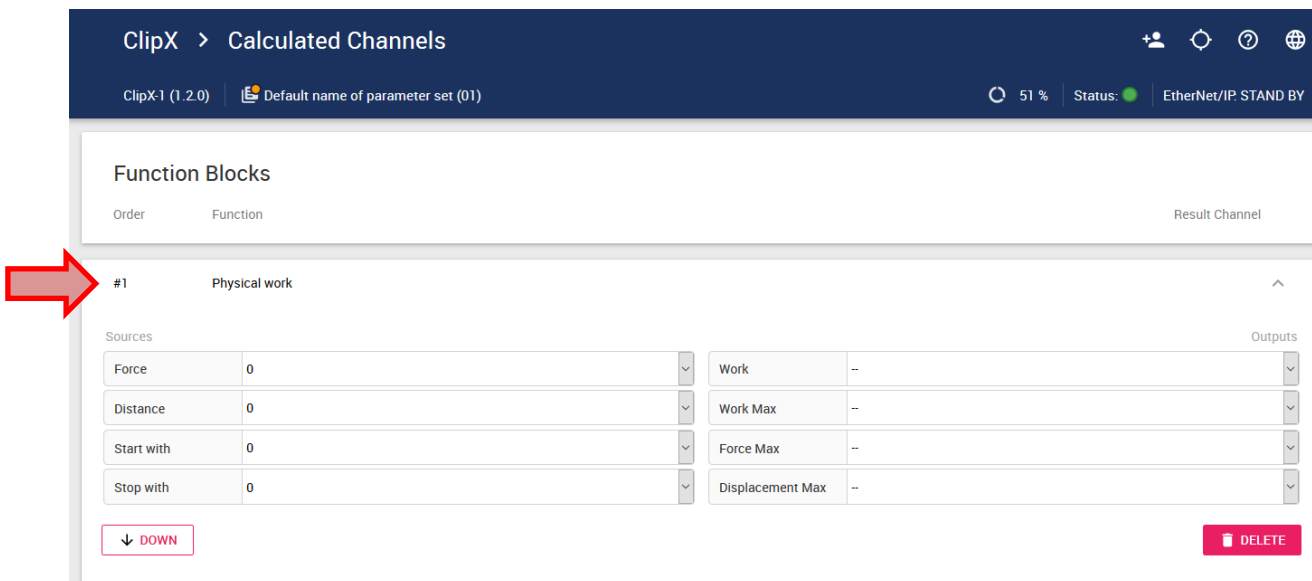
In this menu, names are assigned to the two buses for a better overview (here: force, displacement; yellow framed).

Now both ClipX-systems can work with the signal of the other.

Measurement of the mechanical work

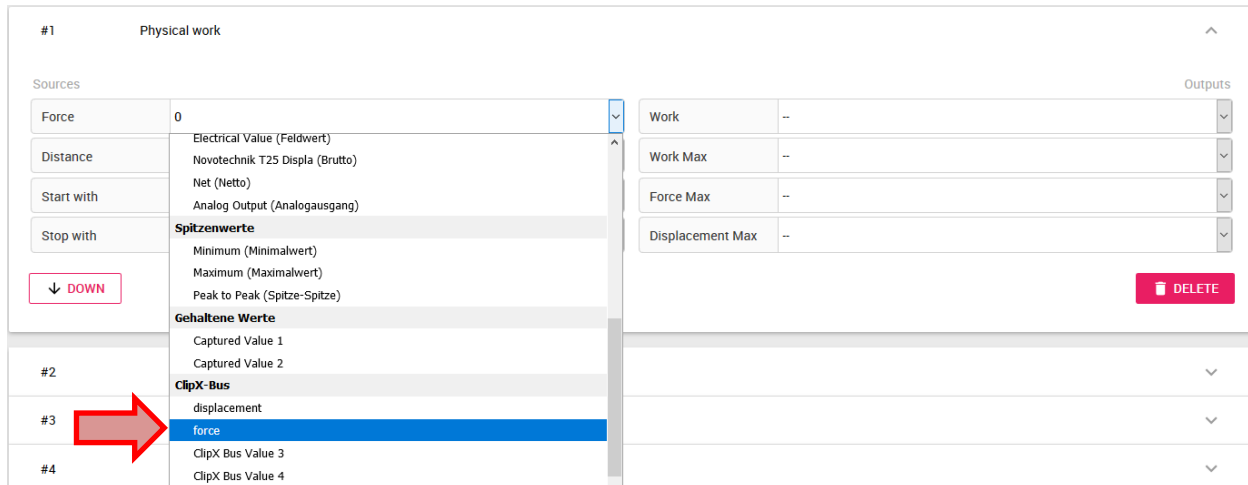
Settings in the ClipX

At first, in the menu item “Calculated Channels” a new function block with type “Physical work” must be added.



Now the sources are defined:

- **Force:** Here you select the ClipX-Bus on which the force signal resides (here: named as "force" in the ClipX-Bus settings).



- **Displacement:** Here you select the ClipX-Bus on which the displacement signal resides (here: named as "displacement" in the ClipX-Bus settings).
- **Start with:** “Digital input 1” is selected here as the start signal (any digital signals are possible here).
- **Stop mit:** “Digital input 2” is selected here as the start signal

Now the settings look like this:

Sources		Outputs	
Force	force	Work	--
Distance	displacement	Work Max	--
Start with	Digital input 1	Force Max	--
Stop with	Digital input 2	Displacement Max	--

↓ DOWN DELETE

Now the Outputs are defined:

Sources		Outputs	
Force	force	Work	Calculated Channel 1
Distance	displacement	Work Max	Calculated Channel 2
Start with	Digital input 1	Force Max	Calculated Channel 3
Stop with	Digital input 2	Displacement Max	Calculated Channel 4

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The calculated channels can be renamed below for a better overview. Also a physical unit can be added.

work actual
Calculated Channel 1

0.000 J

Name
work actual

11 / 22

Decimal Places: Physical Unit:

1 / 10

work max
Calculated Channel 2

0.000 J

Name
work max

8 / 22

Decimal Places: Physical Unit:

1 / 10

force max
Calculated Channel 3

0.000 N

Name
force max

9 / 22

Decimal Places: Physical Unit:

1 / 10

displacement max
Calculated Channel 4

0.000 cm

Name
displacement max

16 / 22

Decimal Places: Physical Unit:

2 / 10

Measurement

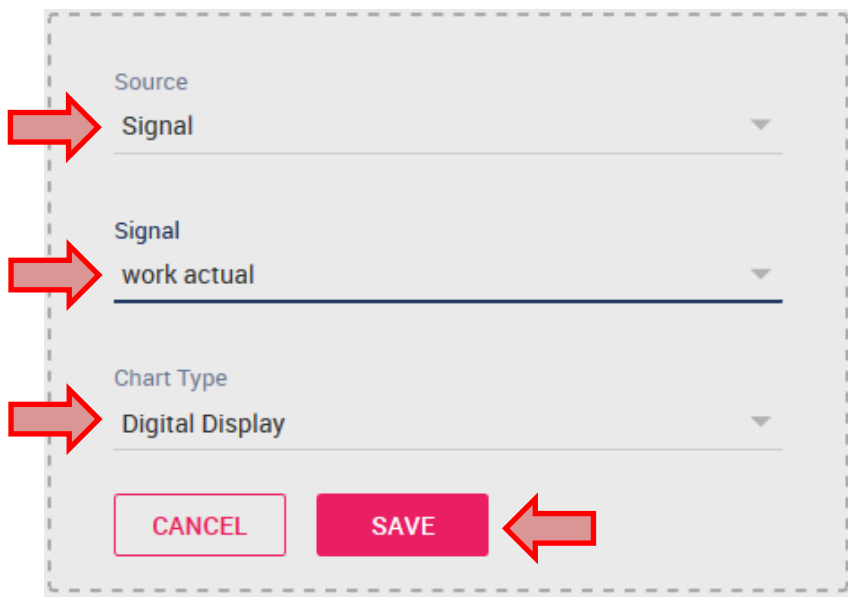
- The measurement starts with the rising flank of digital input 1
- It is finished with the rising flank of digital input 2
- At start of the measurement all measurement values are set to zero

Visualization

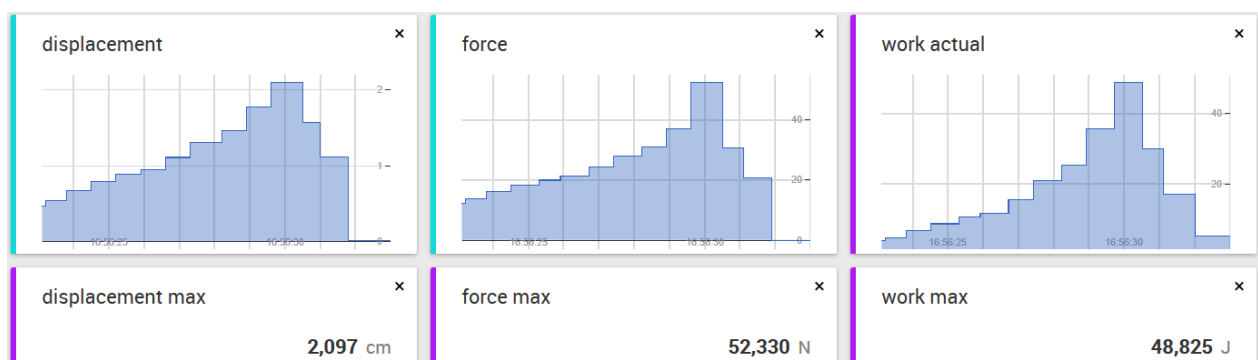
In menu item “Visualization”, the signals can be visualized as y(t)-graph, level display or digital display.

This is shown here as an example for a signal.

Click the “+”-button to add a new signal and make for example the following settings.



The finished visualization for all signals looks like this:



Disclaimer

These examples are for illustrative purposes only. They cannot be used as the basis for any warranty or liability claims.