

Dynamic Power Measurement and How It Can Be Used for Test Optimization

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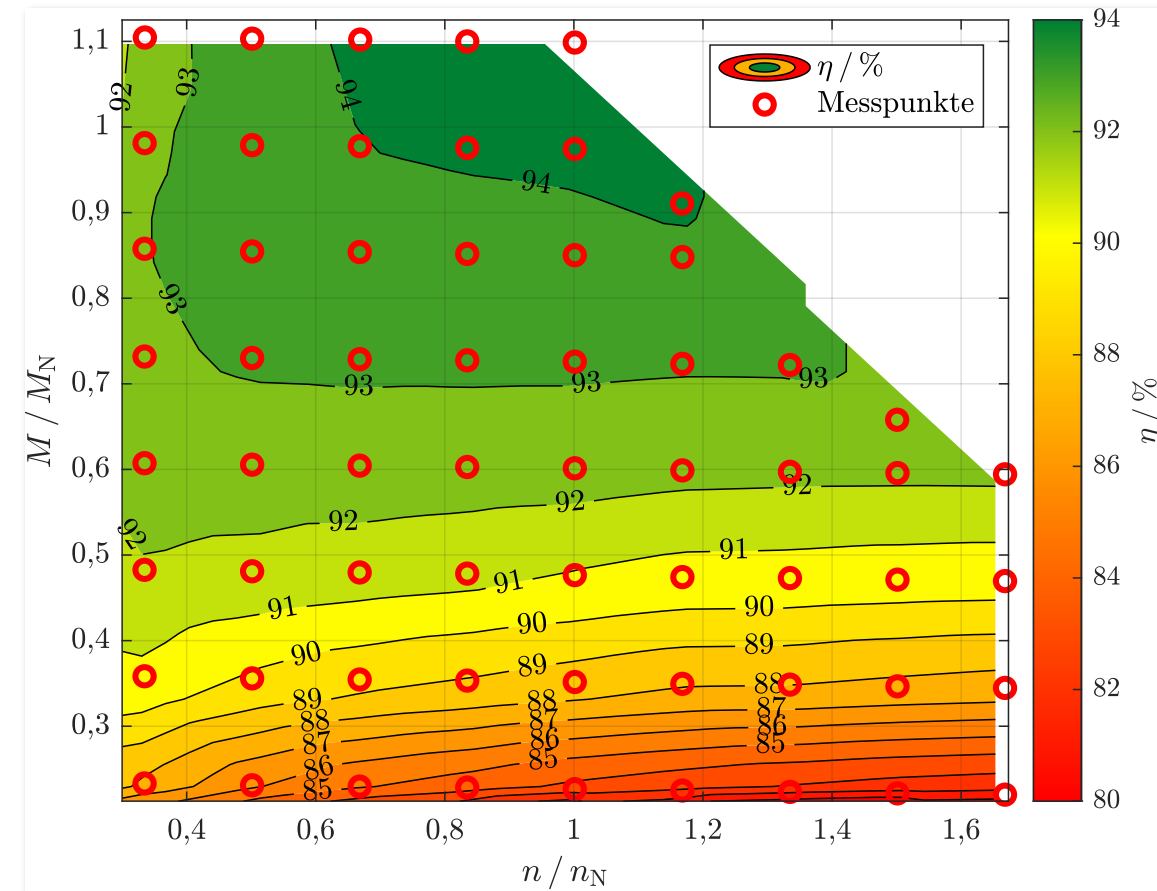
Generating efficiency maps

Efficiency maps for motors and drive trains

- ▲ Range and Cost are conflicting design criteria for an EV
- ▲ More efficient powertrain allow companies to meet these design criteria
- ▲ EV Powertrain operate in a variety of states and operation points
- ▲ Efficiency Maps are a key tool to understand efficiency at all points
- ▲ In the design and drive optimization process, it is therefore important to be able to create and understand many efficiency maps in a short period of time

Efficiency maps for motors and drive trains

- ▲ To be able to determine the efficiency for real use cases, the efficiency is determined in the form of efficiency maps:
 - Efficiency versus torque and speed
 - Different maps for different temperature and voltage combinations
- ▲ The conventional approach:
 - Take a grid of setpoints where the system is in steady-state
 - Interpolate between the measured points to get a continuous efficiency map

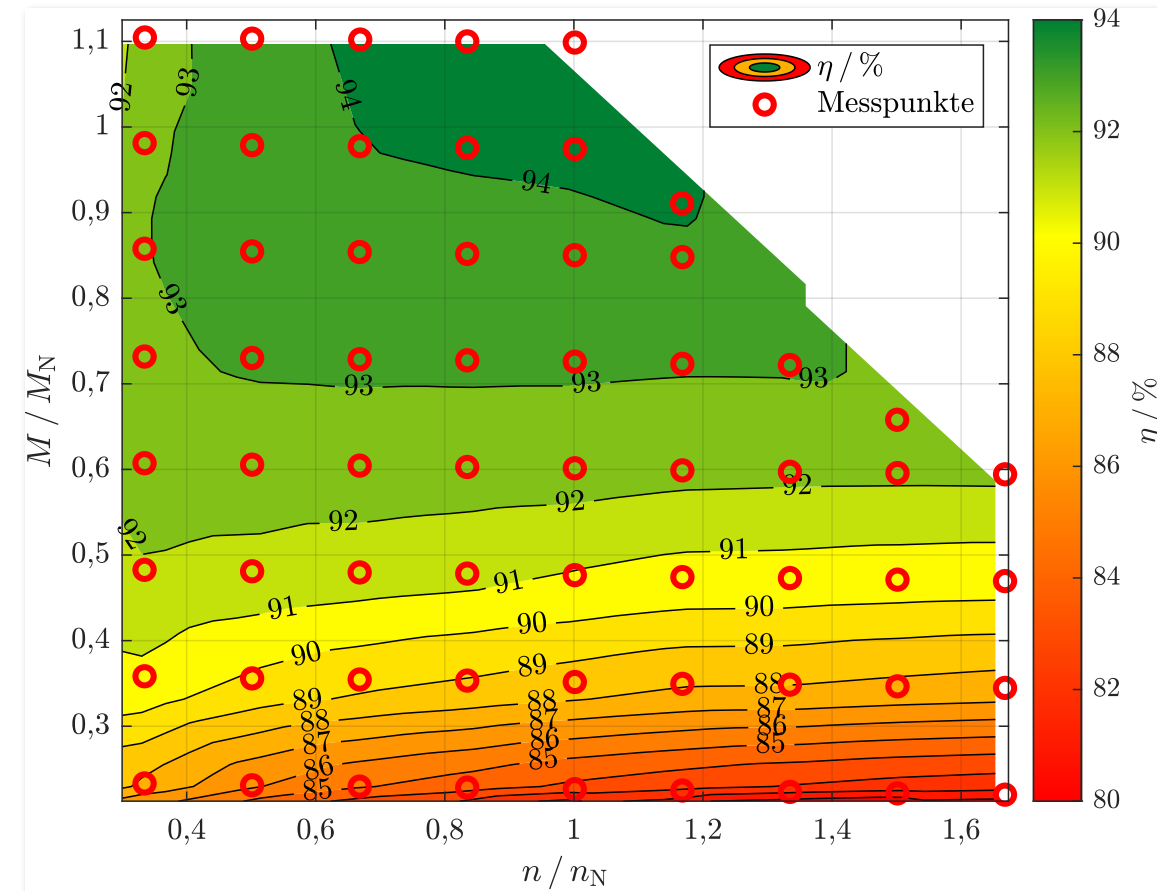


Stock, A.: „Messtechnische Analyse der Energieverluste von stromrichteragespeisten Antriebssystemen im nichtstationären Betrieb“. Dissertation (submitted, not yet published). München: University of the German Federal Armed Forces, 2021

Efficiency maps for motors and drive trains

- ▲ The conventional approach typically contains the following steps
 - Measurement: determine the efficiency of the setup in a single steady-state point
 - Transition: move the setup to the next (torque-speed) setpoint and wait until steady-state is reached
 - Change of parameters: e.g., cooling the system, changing the battery voltage
- ▲ The question:

“How can we reduce the time and cost for generating efficiency maps?”



Measurement Time for Efficiency – Example

▲ States

- 5 temperatures
- 5 battery voltages
- 25 maps

▲ Measurement

- 10 sec with PLL
- 2 sec with cycle detect

▲ Transitions

- 5 sec

▲ Heating up & cooling down

- 100 sec (every 60 seconds)

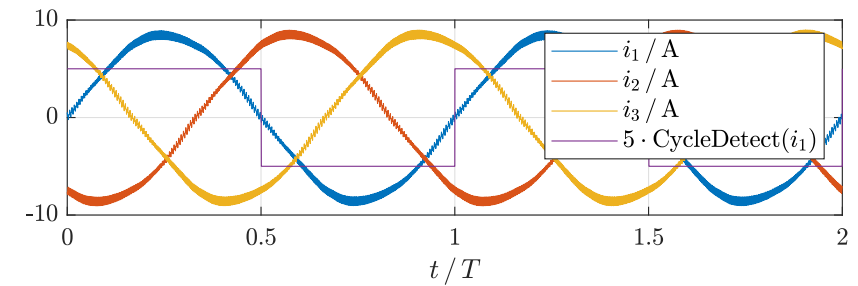
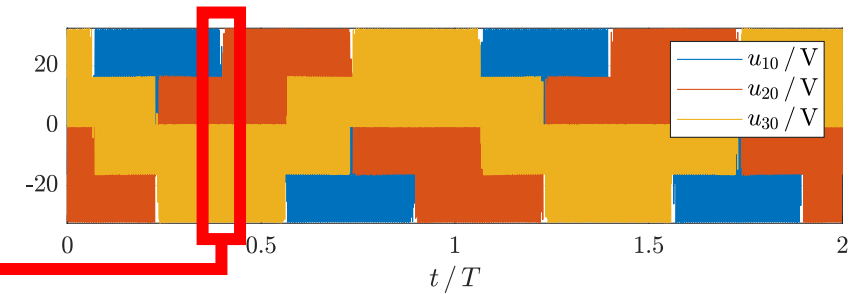
Points/map	10 second Measurement	2 second Measurement
200	46.2 hours	15 hours
600	138.5 hours	45.2 hours
2000	462.0 hours	150.1 hours

Dynamic Testing to Reduce Time → Dynamic Power

Using Dynamic Power Measurements [1]

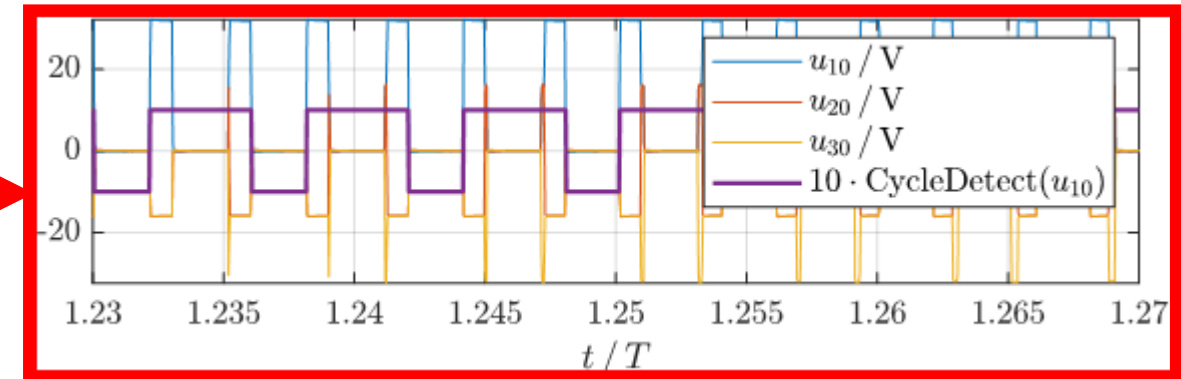
Conventional Power Measurement

- Power is based on fundamental frequency
- the system is brought into steady-state before a measurement is done
- Power is averaged over $\frac{1}{2}$ or more cycles



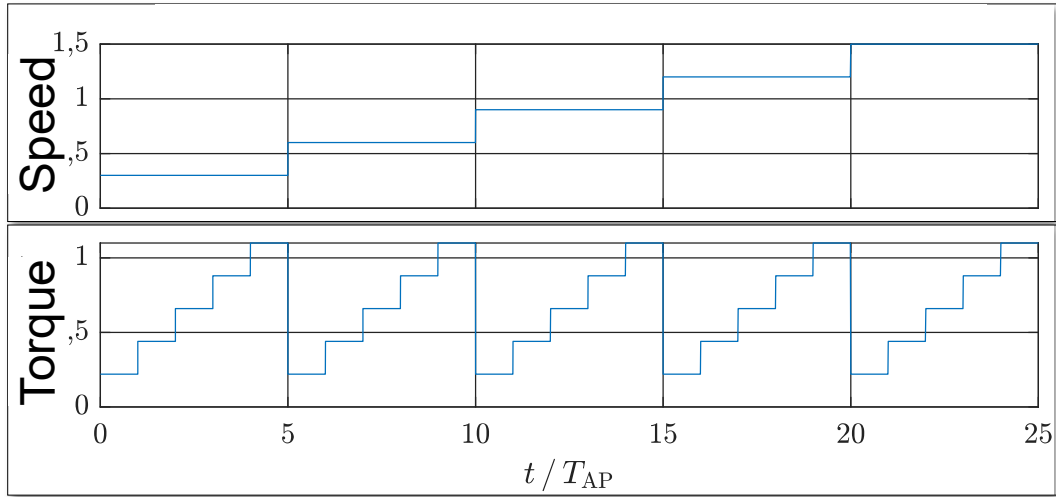
In *Dynamic Power Measurements*

- Power is based on 1 or several *switching periods* of the inverter (think a few *ms*)
- The system moved in a continuous way through the torque-speed curve
- Not as accurate but FAST



[1] Stock, A.: „Messtechnische Analyse der Energieverluste von stromrichter gespeisten Antriebssystemen im nichtstationären Betrieb“. Dissertation. München: University of the German Federal Armed Forces, 2021

Using Dynamic Power Measurements [1]



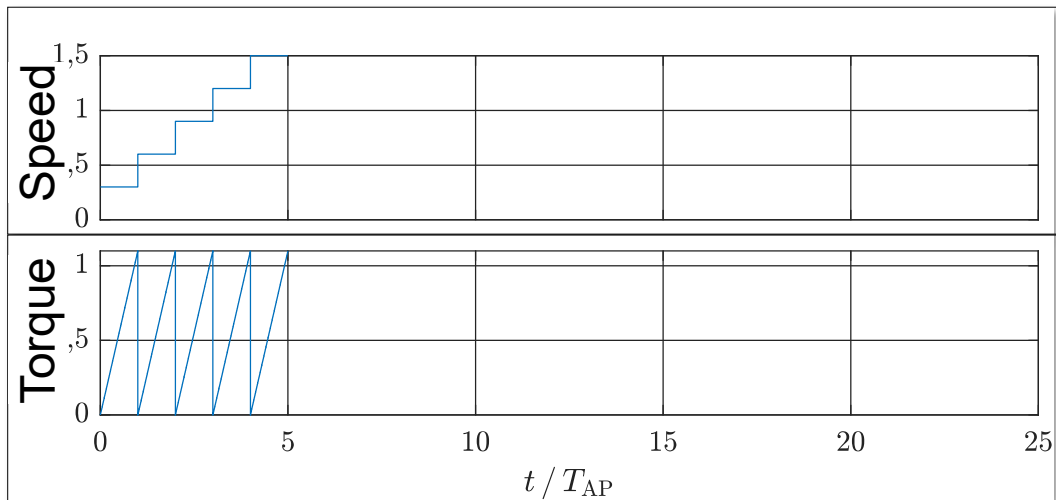
Conventional method

- Steady state setpoint values of speed and torque are driven sequentially
- Conventional active power and mechanical power are calculated based on the fundamental cycle
- Efficiency is calculated

Dynamic method

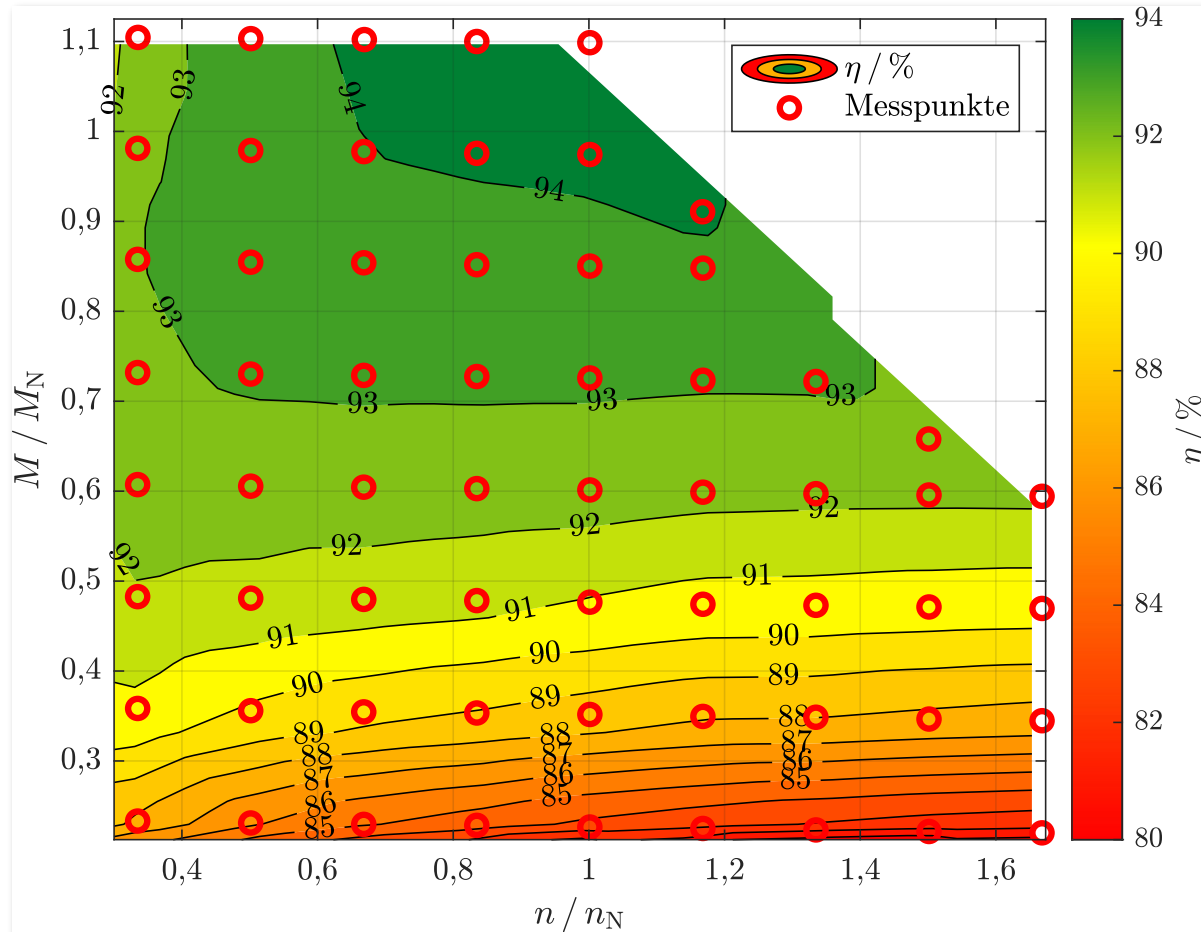
- Steady state state setpoint values of speed are driven sequentially
- For each speed, the torque is ramped up continuously
- Active power and mechanical power are calculated based on the inverter switching cycle

Significant time savings!

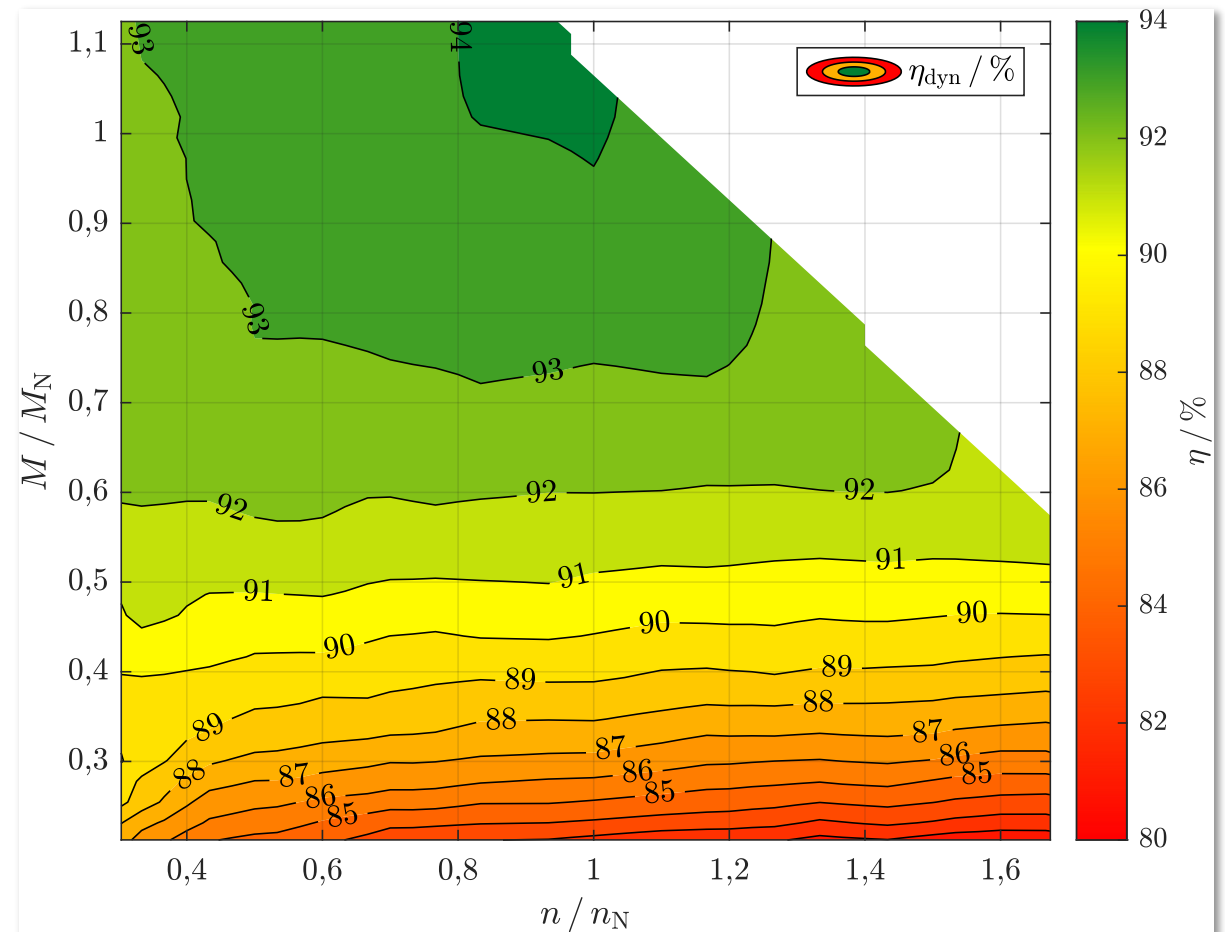


Using Dynamic Power Measurements [1]

Conventional Method



Dynamic Method

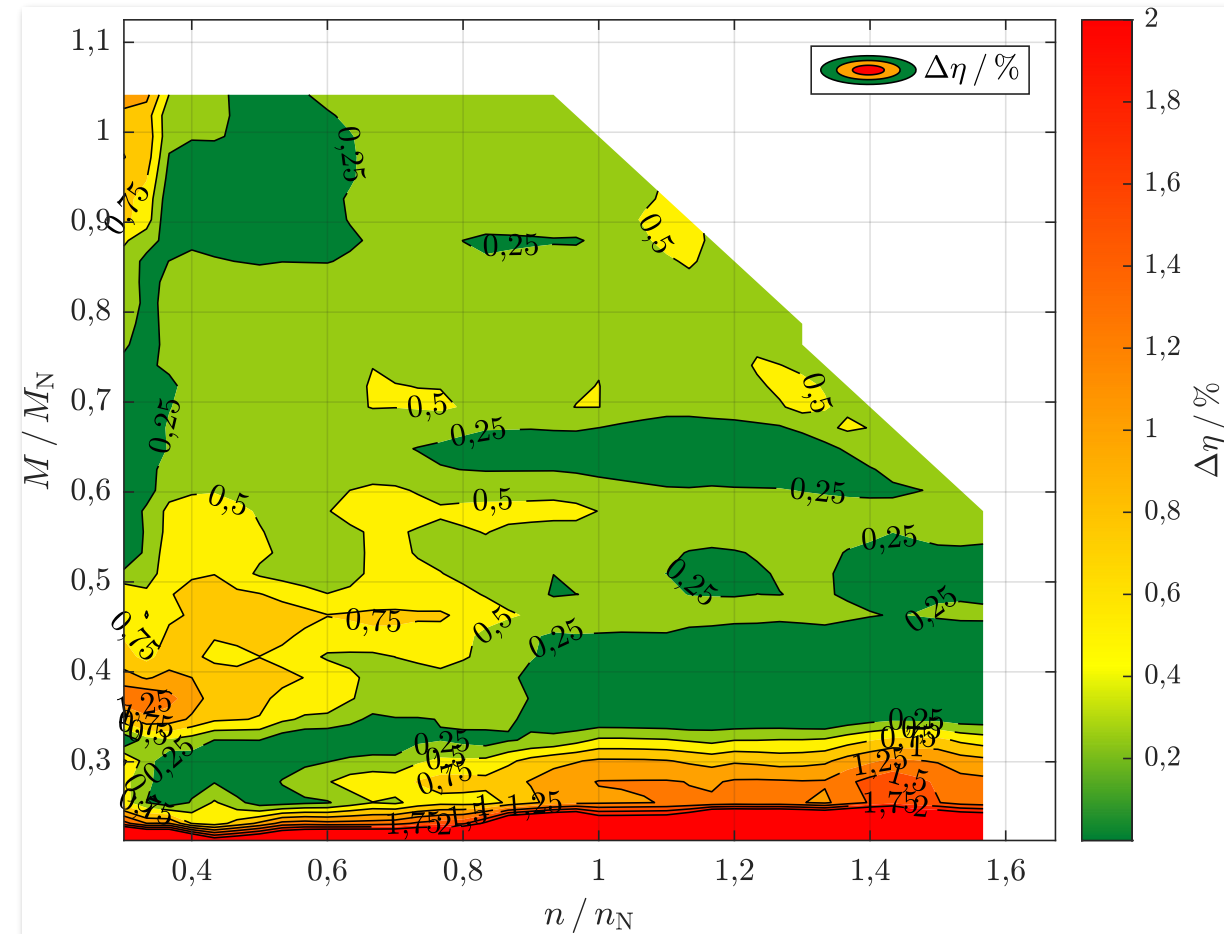


High level of similarity and enormously reduced measurement time

Using Dynamic Power Measurements [1]

- Very small deviation between both methods
 - Small deviation from conventional method is inevitable
 - Not suitable for the highest accuracy requirements
- Accelerated measurement is suitable for
 - End of line tests (pass/fail)
 - Quickly getting a very good estimate of the efficiency plot**
- Can also be used for dyno WLTP
 - no additional efficiency measurement necessary

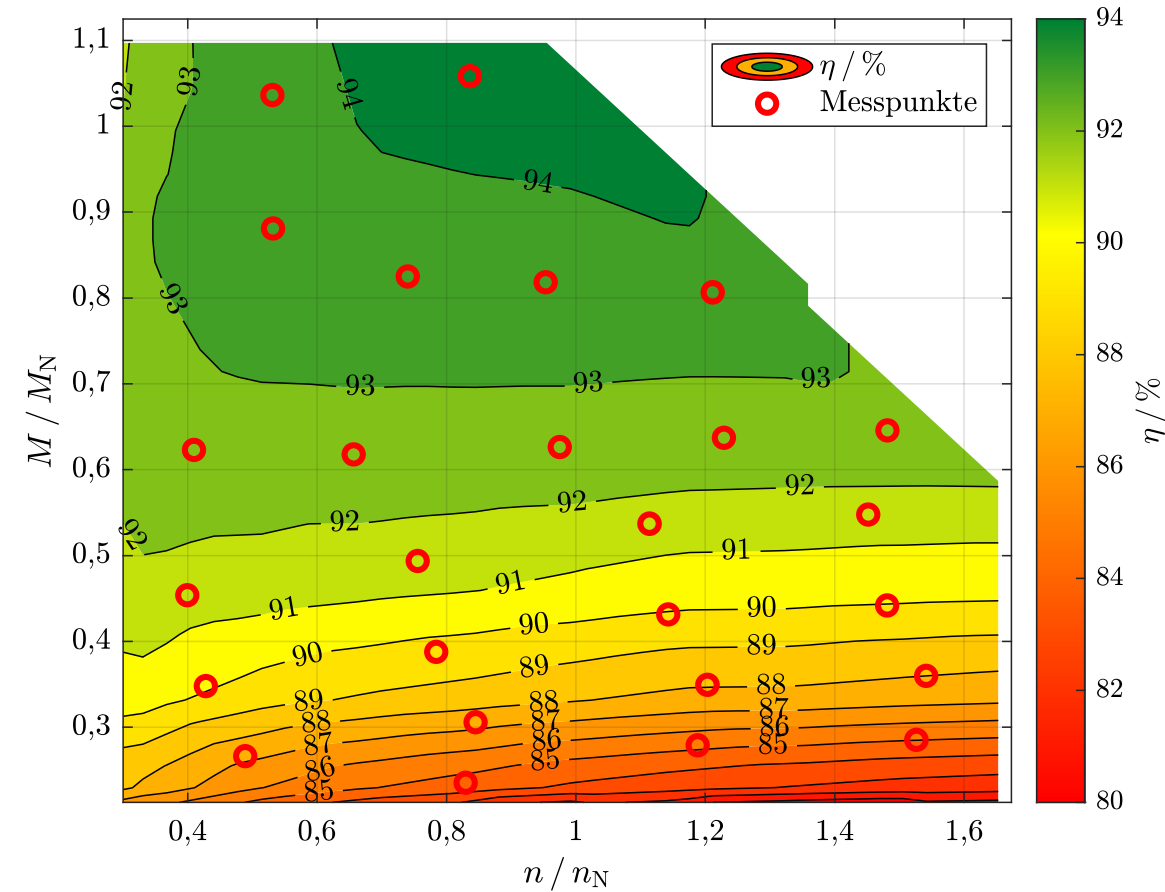
Deviation of Conventional and Dynamic Method



Dynamic Testing to Reduce Time → Optimization

Reducing the number of steady-state setpoints

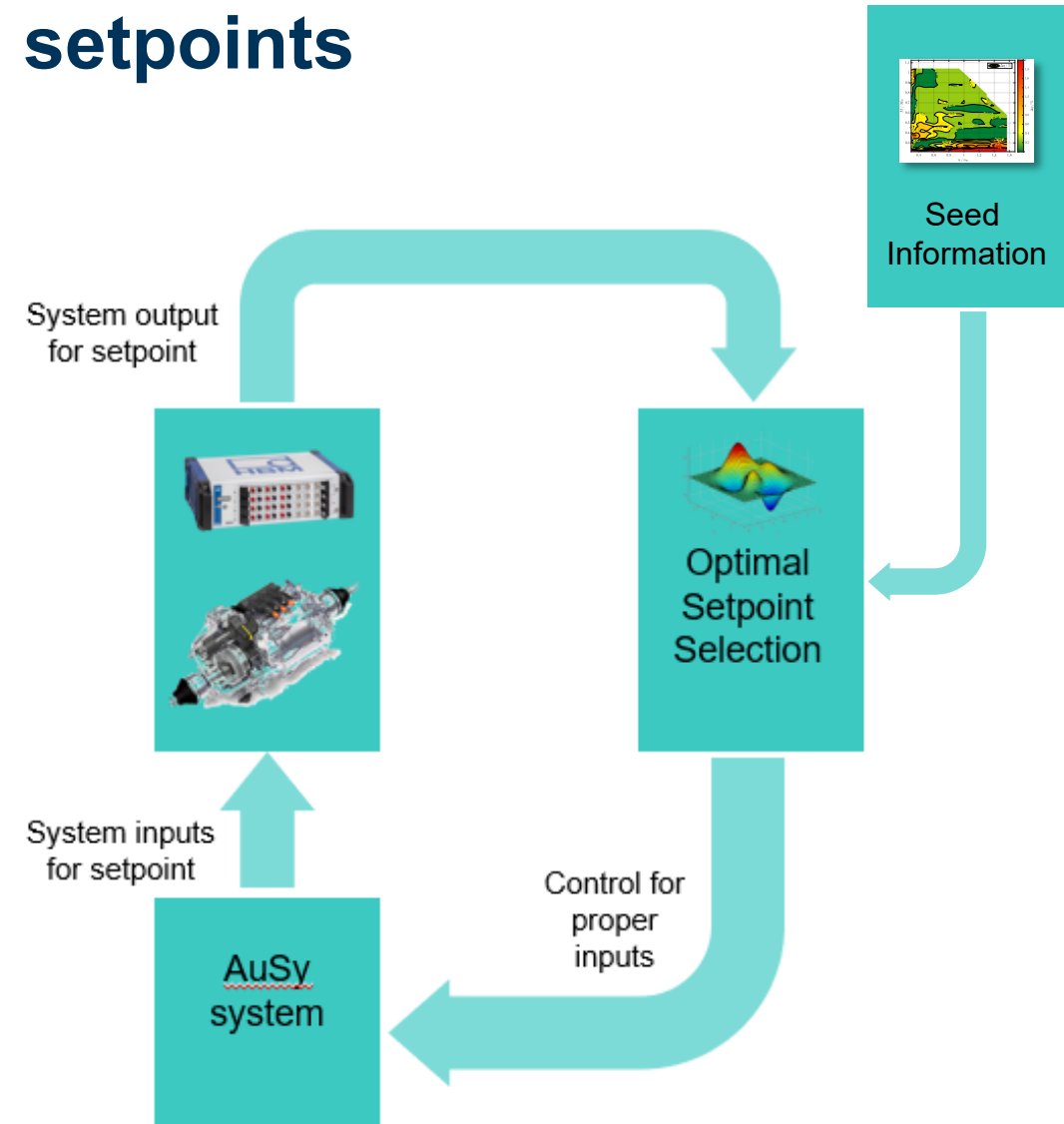
- ▶ Conventional methods use a grid of setpoints and interpolate between them
- ▶ This gives high accuracy efficiency values
- ▶ The total accuracy of the plot depends on how many and where the grid points are chosen
- ▶ “More is better”
 - Longer
 - More expensive
- ▶ **HBK is developing methods that choose the setpoints more efficiently, leading to fewer measuring points but the same accuracy for the efficiency plot**



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Reducing the number of steady-state setpoints

- ▶ Developing a dedicated tool interacting with eDrive and an automation system (AuSy)
- ▶ The tool intelligently chooses optimal setpoints which are then sent to the AuSy
- ▶ The tool uses seed values and live measurements to select the next point
 - Machine parameters
 - **Fast efficiency sweep**
 - Drive cycles
 - Models & simulation



Measurement Time for Efficiency – Point Reduction

▲ 30% point reduction

▲ Conditions

- States
 - 25 maps
- Measurement
 - 2 sec with cycle detect
- Transitions
 - 5 sec
- Heating up & cooling down
 - 100 sec (every 60 seconds)
- Other Tests & Downtime

Equivalent Points/map	Non - Optimized	30% Reduction	Savings at \$2500/day
200	15 hours	10.5 hours	\$1,412.76
600	45.2 hours	31.6 hours	\$4,238.28
2000	150.1 hours	105.5 hours	\$14,127.60

▲ How many tests do you run a year?

Discussion

- ▲ We sketched two approaches to reduce the time and cost for generating efficiency maps
- ▲ What are your thoughts?
 - Any feedback on the proposed methodologies?
 - Would those methods work practically in your environment? (Think of the machine heating up during Dynamic Power measurements)
 - Is the efficiency accuracy equally important over the whole plot, or do you want higher accuracy in certain areas?
 - ...
- ▲ Future
 - Model correlation
 - Model refinement
 - Automated Tuning

Thank you!