

T22

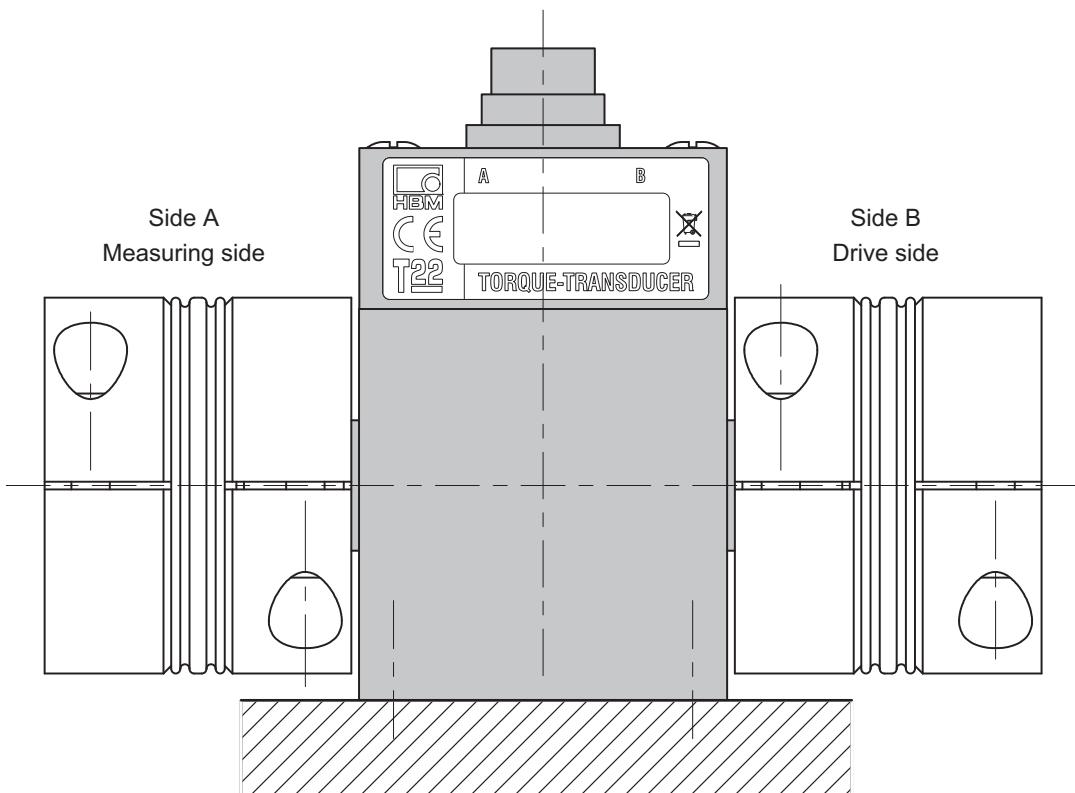
Torque transducer



Special features

- Nominal (rated) torques 0.5 Nm, 1 Nm, 2 Nm, 5 Nm, 10 Nm, 20 Nm, 50 Nm, 100 Nm, 200 Nm, 500 Nm and 1 kNm
- Nominal (rated) rotational speed up to 20000 rpm (depending on measuring range)
- Accuracy class: 0.5
- Contactless transmission of measurement signals
- Measurement on rotating or stationary parts
- Cylindrical shaft ends for non-play friction joints
- ± 5 V and 10 ± 8 mA torque output signal

Installation example with two bellows couplings



Specifications

Type		T22									
Accuracy class		0.5									
Torque measuring system											
Nominal (rated) torque M_{nom}	N·m	0.5	1	2	5	10	20	50	100	200	500
	kN·m										1
Nominal (rated) sensitivity (span between torque = zero and nominal (rated) torque M_{nom})	V mA	5 8									
Voltage output Current output	% %	± 0.5 ± 0.5									
Sensitivity tolerance (deviation of the actual output quantity at M_{nom} from the nominal (rated) sensitivity)											
Voltage output Current output	% %	0 ± 0.2 10 ± 0.2									
Output signal at torque = zero	V mA										
Voltage output Current output											
Nominal (rated) output signal											
Voltage output at positive nominal (rated) torque at negative nominal (rated) torque	V V	+5 -5									
Current output at positive nominal (rated) torque at negative nominal (rated) torque	mA mA	+18 +2									
Load resistance (Voltage output)	MΩ	>1									
Burden (current output)											
with $U_B = 12 \text{ V}$ with $U_B = 24 \text{ V}$	Ω Ω	250 500									
Longterm drift over 48h											
Voltage output Current output	mV μA	$< \pm 50$ $< \pm 80$									
Cut-off frequency (-3 dB) (volt. output / current output)	kHz	1									
Group delay (voltage output / current output)	μs	450									
Residual ripple											
Voltage output Current output	mV _{pp} mA _{pp}	< 100 < 0.1									
Effect of temperature per 10 K in the nominal (rated) temperature range											
on the output signal , related to the actual value of the signal span	%	$\leq \pm 0.2$									
on the zero signal , relat. to the nominal (rated) sensitivity	%	$\leq \pm 0.5$									
Power supply											
Nominal (rated) supply voltage range	V (DC)	11.5 ... 30									
Current consumption in measuring mode	A	< 0.2									
Nominal (rated) power consumption	W	< 2.4									
Permissible residual ripple of supply voltage	mV _{pp}	200									
Linearity error including hysteresis , related to the nominal (rated) sensitivity	%	$\leq \pm 0.3$									
Rel. standard deviation of repeatability per DIN 1319, related to the variation of the output signal	%	$\leq \pm 0.1$									
Max. level control range¹⁾ voltage output / current output	%	≤ 120									

1) Output signal range in which there is a repeatable correlation between torque and output signal.

Specifications (continued)

Nominal (rated) torque M_{nom}	N·m	0.5	1	2	5	10	20	50	100	200	500	
	kN·m											1
General data												
EMC²⁾												
Immunity from interference (DIN EN 61326-1 / EN 61000-6)												
Enclosure												
HF line interference 150 kHz - 80 MHz (AM)	V											10 / A
ESD (electrostatic discharge)	KV											Air 8 / A
	KV											Contact 4 / A
Enclosure												
Electromagnetic field 80 MHz - 1000 MHz (AM)	V/m											10 / A
1400 MHz - 2700 MHz (AM)	V/m											3 / A
Lines - Connecting cable Burst (fast transients)	kV											2 / A
Emission (EME) (EN 61326-1 / EN 55011)												
RFI voltage (interference voltage at DC mains connection)	-											Class B (150 kHz - 30 MHz)
RFI field strength (Electromagnetic RFI field strength)	-											Class B (30 MHz - 1000 MHz)
Degree of protection per EN 60 529												IP 40
Nominal (rated) temperature range	°C [°F]											+5...+45 [+41...+113]
Operating temperature range	°C [°F]											0...+60 [+32...+140]
Storage temperature range	°C [°F]											-5...+70 [+23...+158]
Impact resistance, test severity level per DIN IEC 68; Part 2-27; IEC 68-2-29-1987												
number	n											1000
duration	ms											3
acceleration (halfsine)	m/s ²											650
Vibration resistance, test severity level per DIN IEC 68, Part 2-6: IEC 68-2-6-1982												
frequency range	Hz											5 ... 65
duration	h											1.5
acceleration (amplitude)	m/s ²											50
Nominal (rated) rotational speed n_{nom}	min ⁻¹											20 000 16 000 12 000 9 000
Load limits³⁾												
Limit torque, related to M_{nom}	%											200 ⁵⁾
Breaking torque, related to M_{nom}	%											> 280
Longitudinal limit force	kN	0.19	0.19	0.19	0.9	0.9	0.9	1.6	1.6	1.6	4	4
Lateral limit force	N	30	30	60	25	45	90	210	420	850	1400	2800
Bending limit moment	N·m	0.3	0.3	0.5	0.5	0.9	1.9	5.5	11	22	54	109
Oscillation width per DIN 50100 (peak-topeak)⁴⁾	%											80

2) Test severity / criterion: Industrial environment, cable length ≤ 30 m. Application not outside buildings.

3) Each type of irregular stress (bending moment, lateral or longitudinal force, exceeding nominal (rated) torque) can only be permitted up to its specified static load limit provided none of the others can occur at the same time. If this condition is not met, the limit values must be reduced. If 30% of the bending limit moment and lateral limit force occur at the same time, only 40% of the longitudinal limit force is permissible and the nominal (rated) torque must not be exceeded. The permissible bending moments, longitudinal forces and lateral forces can affect the measurement result by approx. 1 % of the nominal (rated) torque.

4) The nominal (rated) torque must not be exceeded.

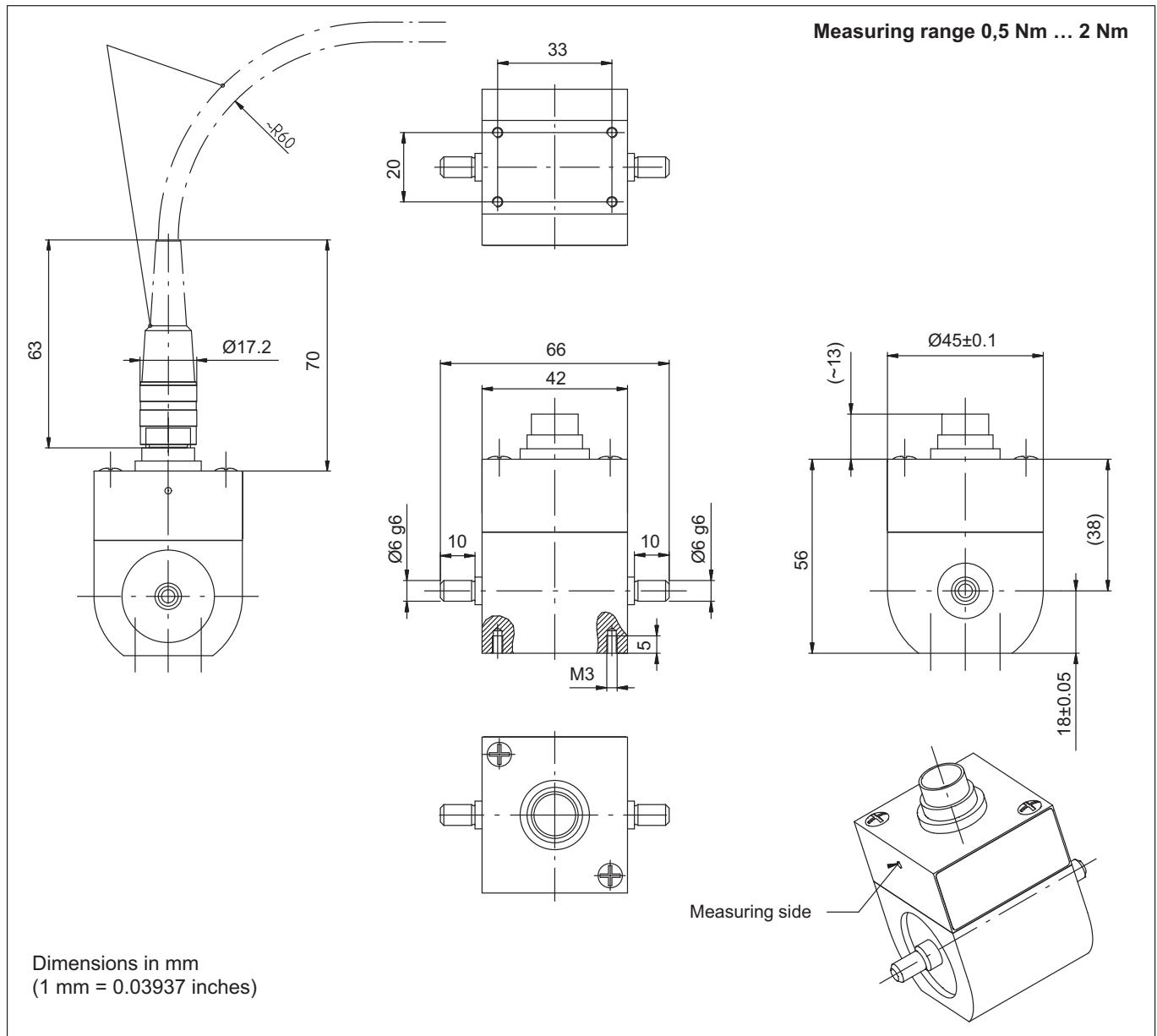
5) Please adhere to the maximum torque (T_{max}) of the couplings.

Specifications (continued)

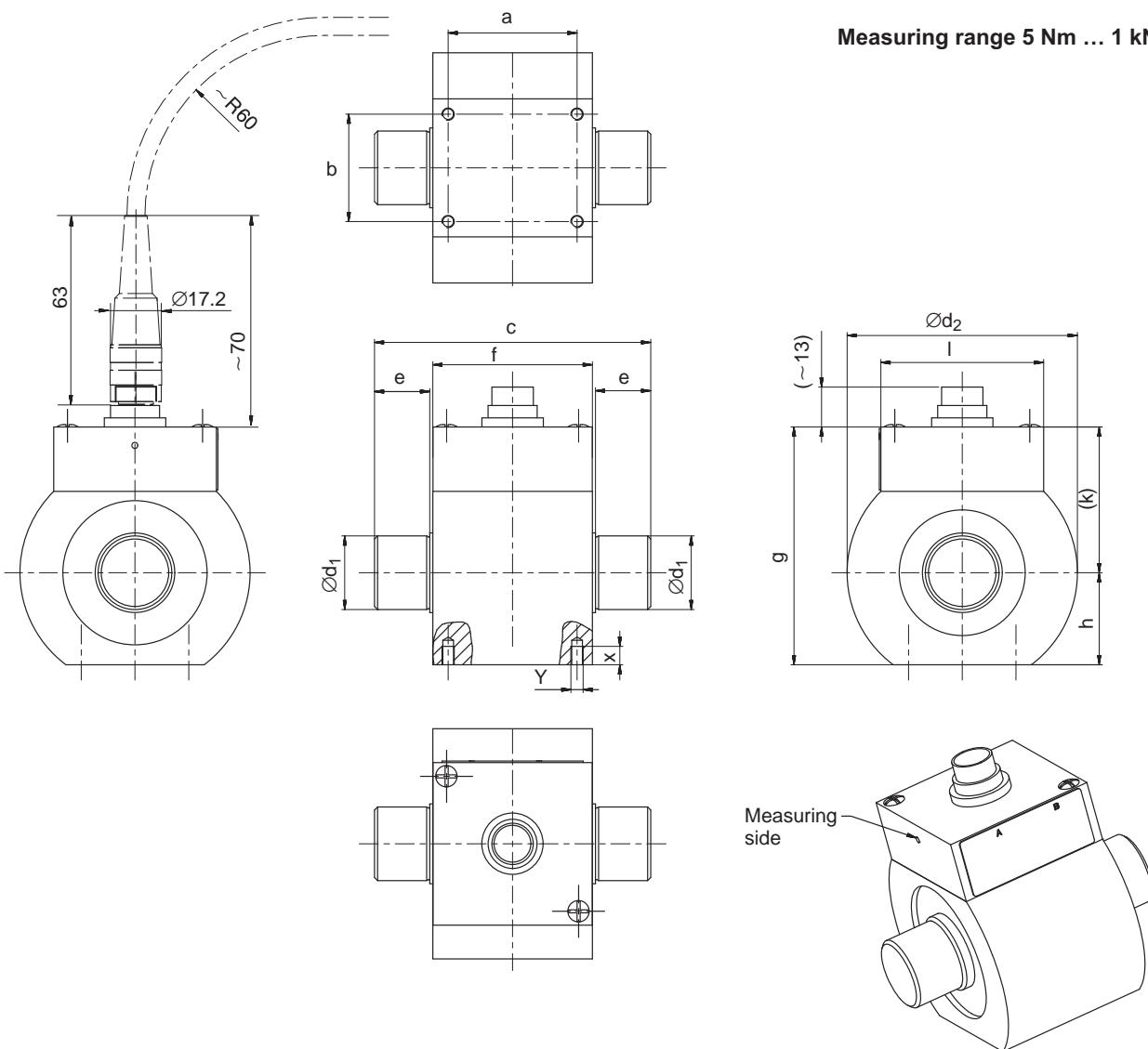
Nominal (rated) torque M_{nom}	N·m	0.5	1	2	5	10	20	50	100	200	500	
	kN·m											1
Mechanical values												
Torsional stiffness c_T	kN·m/ rad	0.14	0.14	0.29	1.1	2.7	5.4	19.7	35.5	52.4	288. 6	418. 9
Torsion angle at M_{nom}	Deg.	0.20	0.39	0.39	0.26	0.21	0.21	0.15	0.16	0.22	0.10	0.14
Balance quality-level per DIN ISO 1940								G 6.3				
Max. limits for relative shaft vibration (peakto-peak) ⁶⁾	μm							$s_{\text{max}} = \frac{4500}{\sqrt{n}}$	(n in rpm)			
Rms value for the vibration velocity of the enclosure designated in VDI 2056	mm/s							$v_{\text{eff}} = \frac{\sqrt{n}}{3}$	(n in rpm)			
Mass moment of inertia												
total		1.5	1.5	1.5	13.4	13.5	13.6	39.8	40.5	42.4	335. 0	351. 9
drive side of shaft	10^{-3} g·m ²	0.145	0.145	0.145	11.6	11.7	11.7	29.2	29.6	30.5	187. 9	196. 3
measuring side of shaft		0.05	0.05	0.05	1.8	1.8	1.9	10.6	10.9	11.9	147. 1	155. 6
Weight	g	230			550			850			2400	

6) Relative undulation in the area of the connecting shaft stubs, following DIN 45670/VDI 2059

Dimensions of the T22



Measuring range 5 Nm ... 1 kNm



Measuring range (N·m)	Dimensions (in mm)												
	a	b	c	e	f	g	h ± 0.05	(k)	l	$\varnothing d_1$ g6	$\varnothing d_2 \pm 0.1$	Y	X
5													
10	39	31	80	15	48	72	28	44	52.75	15	70	M4	6
20													
50													
100	42	35	90	18	52	77.5	30	47.5	53	24	75	M4	6
200													
500													
1k	50	55	120	26	65	97.5	40	57.5	75.5	40	105	M5	10

Accessories for the T22, to be ordered separately

Transducer connection cable, 5 m long, order no. 3-3301.0158

Transducer connection cable, 10 m long, order no. 3-3301.0159

Cable socket, 12-pin (Binder), order no. 3-3312.0268

Bellows couplings

Junction box, order no. 1-VK20A

Accessories for junction box VK20A, to be ordered separately

Connection cable, 1.5 m long (D-Sub, 15-pin - free ends), order no. 1-KAB151A-1.5

Connection cable, 1.5 m long (SUBCON5 - free ends), order no. 1-KAB152-1.5

Subject to modifications.

All product descriptions are for general information only. They are not to be understood as a guarantee of quality or durability.

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